T-61.5030 Advanced course in neural computing

Solutions for exercise 7

1. If we are not interested in the dependencies inside the groups \mathbf{X}_1 or \mathbf{X}_2 but are interested only on dependecies between these groups, we can use canonical correlation analysis (CCA). It means that we try to find projections from \mathbf{X}_1 and \mathbf{X}_2 which would be as correlated as possible. CCA uses only second-order statistics; for Gaussian variables this is sufficient but CCA can also be used for non-Gaussian variables. For a tutorial on CCA, see, e.g., the one by Magnus Borga available at http://people.imt.liu.se/~magnus/cca/. The following is partly based on the information in that tutorial.

The correlation coefficient between zero mean random variables a and b is defined to be $\rho_{ab} = E\{ab\}/\sqrt{E\{a^2\}E\{b^2\}}$. We have projections $a_i = \mathbf{u}_i^T \mathbf{x}_1$ and $b_i = \mathbf{v}_i^T \mathbf{x}_2$ and we would like to maximise the correlations between a_i and b_i . We restrict the solutions to be uncorrelated for different i: $E\{a_ia_j\} = E\{b_ib_j\} = E\{a_ib_j\} = 0$ for $i \neq j$.

For the ith projections we have

$$\rho_{a_i b_i} = \frac{E\{\mathbf{u}_i^T \mathbf{x}_1 \mathbf{x}_2^T \mathbf{v}_i\}}{\sqrt{E\{\mathbf{u}_i^T \mathbf{x}_1 \mathbf{x}_1^T \mathbf{u}_i\} E\{\mathbf{v}_i^T \mathbf{x}_2 \mathbf{x}_2^T \mathbf{v}_i\}}} = \frac{\mathbf{u}_i^T E\{\mathbf{x}_1 \mathbf{x}_2^T\} \mathbf{v}_i}{\sqrt{\mathbf{u}_i^T E\{\mathbf{x}_1 \mathbf{x}_1^T\} \mathbf{u}_i \mathbf{v}_i^T E\{\mathbf{x}_2 \mathbf{x}_2^T\} \mathbf{v}_i}} = \frac{\mathbf{u}_i^T \boldsymbol{\Sigma}_{12} \mathbf{v}_i}{\sqrt{\mathbf{u}_i^T \boldsymbol{\Sigma}_{11} \mathbf{u}_i \mathbf{v}_i^T \boldsymbol{\Sigma}_{21} \mathbf{v}_i}}.$$

It can be shown that the maximization corresponds to solving either one of the following eigenvalue equations:

$$\begin{split} \mathbf{\Sigma}_1^{-1} \mathbf{\Sigma}_{12} \mathbf{\Sigma}_2^{-1} \mathbf{\Sigma}_{12}^T \mathbf{u}_i &= \rho_{a_i b_i}^2 \mathbf{u}_i \\ \mathbf{\Sigma}_2^{-1} \mathbf{\Sigma}_{12}^T \mathbf{\Sigma}_1^{-1} \mathbf{\Sigma}_{12} \mathbf{v}_i &= \rho_{a_i b_i}^2 \mathbf{v}_i \;. \end{split}$$

Connection to singular value decomposition. Canonical correlations are invariant to affine transformations (for example, if a transformation \mathbf{A} is used for \mathbf{x}_1 , just set $\hat{\mathbf{u}}_i = \mathbf{A}^{-1}\mathbf{u}_i$). Therefore, to simplify the situation, suppose that \mathbf{X}_1 and \mathbf{X}_2 have been whitened (see problem 4 for the precise transformations needed). Then $\boldsymbol{\Sigma}_1 = \mathbf{I}$ and $\boldsymbol{\Sigma}_2 = \mathbf{I}$. (Note that \mathbf{X}_1 and \mathbf{X}_2 can have different dimensionalities, so the two identity matrices can be of different sizes.) The eigenvalue equations then become

$$\boldsymbol{\Sigma}_{12} \boldsymbol{\Sigma}_{12}^T \mathbf{u}_i = \rho_{a_i b_i}^2 \mathbf{u}_i , \ \boldsymbol{\Sigma}_{12}^T \boldsymbol{\Sigma}_{12} \mathbf{v}_i = \rho_{a_i b_i}^2 \mathbf{v}_i .$$
(1)

Solving the above equations corresponds to singular value decomposition (SVD) of Σ_{12} . SVD is similar to eigendecomposition but the orthogonal matrices need not be the same. This also means the SVD can be extended for non-square matrices. The singular value decomposition for matrix $\Sigma_{12} = E\{\mathbf{x}_1\mathbf{x}_2^T\}$ gives a decomposition $\Sigma_{12} = \mathbf{U}\mathbf{D}\mathbf{V}^T$, where \mathbf{U} and \mathbf{V} are orthogonal square matrices and \mathbf{D} is a matrix which has non-zero elements only on its diagonal. Notice that **D** has the same shape as Σ_{12} and it is therefore not necessarily square. The matrices **U** and **V** are computed by eigendecomposition:

$$\Sigma_{12} = \mathbf{U}\mathbf{D}\mathbf{V}^T \Rightarrow \begin{cases} \Sigma_{12}\Sigma_{12}^T = \mathbf{U}\mathbf{D}\mathbf{V}^T\mathbf{V}\mathbf{D}^T\mathbf{U}^T = \mathbf{U}\mathbf{D}\mathbf{D}^T\mathbf{U}^T \text{ and} \\ \Sigma_{12}^T\Sigma_{12} = \mathbf{V}\mathbf{D}^T\mathbf{U}^T\mathbf{U}\mathbf{D}\mathbf{V}^T = \mathbf{V}\mathbf{D}^T\mathbf{D}\mathbf{V}^T. \end{cases}$$
(2)

Therefore **U** and **V** are the same as the solutions to the eigenvalue equations (1): $\mathbf{U} = [\mathbf{u}_1 \dots \mathbf{u}_n]^T$ and $\mathbf{V} = [\mathbf{v}_1 \dots \mathbf{v}_m]^T$ and the diagonal elements of **D** are the corresponding correlation coefficients ρ_i .

Note: SVD can be seen as an extension to eigendecomposition. If SVD is done for the covariance matrix $\Sigma_1 = E\{\mathbf{x}_1\mathbf{x}_1^T\}$, we have $\Sigma_1\Sigma_1^T = \Sigma_1^T\Sigma_1$ and $\mathbf{D}\mathbf{D}^T = \mathbf{D}^T\mathbf{D}$ in equation (2), and the orthogonal matrices **U** and **V** are therefore the same. The diagonal matrix then contains the eigenvalues which can be interpreted as variances to the directions given by the eigenvectors. For Σ_{12} the diagonal elements give the correlation coefficients (assuming that Σ_{12} is computed for the whitehed data).

2. (a) We shall use subindices k and l instead of i and j in order to avoid confusion with the $i = \sqrt{-1}$. Denote the Fourier transform of the sequence $x_k(t)$ by $X_k(\omega)$ and the Fourier transform of $s_l(t)$ by $S_l(\omega)$. Recall that the Fourier transform changes a delay by D_{kl} into multiplication with term $e^{i\omega D_{kl}}$. Fourier transforming both sides of the equation defining the mixtures thus yields

$$X_k(\omega) = \sum_{l=1}^N a_{kl} e^{i\omega D_{kl}} S_l(\omega) \,.$$

This can be written as $\mathbf{X}(\omega) = \mathbf{A}(\omega)\mathbf{S}(\omega)$ when \mathbf{X} and \mathbf{S} are defined to be the vectors containing X_k and S_l and

$$\mathbf{A}(\omega) = \begin{pmatrix} a_{11}e^{i\omega D_{11}} & \cdots & a_{1N}e^{i\omega D_{1N}} \\ \vdots & \ddots & \vdots \\ a_{M1}e^{i\omega D_{M1}} & \cdots & a_{MN}e^{i\omega D_{MN}} \end{pmatrix}$$

Notice that **A** is not constant.

- (b) Since the original a_{kl} are real, we have $a_{kl} = \pm |A_{kl}|$, where A_{kl} denotes the element of matrix **A**.
- 3. Assume that x_1 and x_2 are independent random variables. The kurtosis (fourth-order cumulant) of a random variable y is defined by

$$kurt(y) = E\{(y - E\{y\})^4\} - 3(E\{(y - E\{y\})^2\})^2.$$

Let us prove that $kurt(x_1 + x_2) = kurt(x_1) + kurt(x_2)$. We may without loss of generality assume that x_1 and x_2 are zero-mean. Then the kurtosis of $x_1 + x_2$ is

$$kurt(x_1 + x_2) = E\{(x_1 + x_2)^4\} - 3(E\{(x_1 + x_2)^2\})^2$$
$$= E\{x_1^4 + 4x_1^3x_2 + 6x_1^2x_2^2 + 4x_1x_2^3 + x_2^4\} - 3(E\{x_1^2 + 2x_1x_2 + x_2^2\})^2$$

Expectation is a linear operation, i.e. $E\{\alpha y_1 + \beta y_2\} = \alpha E\{y_1\} + \beta E\{y_2\}$ for random variables y_1 and y_2 and scalar multipliers α and β . The above formula can therefore be rewritten as

$$kurt(x_1 + x_2) = E\{x_1^4\} + 4E\{x_1^3x_2\} + 6E\{x_1^2x_2^2\} + 4E\{x_1x_2^3\} + E\{x_2^4\}$$
$$-3(E\{x_1^2\} + 2E\{x_1x_2\} + E\{x_2^2\})^2$$
$$= E\{x_1^4\} + 4E\{x_1^3x_2\} + 6E\{x_1^2x_2^2\} + 4E\{x_1x_2^3\} + E\{x_2^4\}$$
$$-3E\{x_1^2\}^2 - 12E\{x_1^2\}E\{x_1x_2\} - 6E\{x_1^2\}E\{x_2^2\}$$
$$-12E\{x_1x_2\}^2 - 12E\{x_1x_2\}E\{x_2^2\} - 3E\{x_2^2\}^2.$$

Since x_1 and x_2 are independent, $E\{x_1^p x_2^q\} = E\{x_1^p\}E\{x_2^q\}$, for all $q, p \in \{1, \ldots, 4\}$. Then the above formula can be further rewritten:

$$kurt(x_1 + x_2) = E\{x_1^4\} + 4E\{x_1^3\}E\{x_2\} + 6E\{x_1^2\}E\{x_2^2\} + 4E\{x_1\}E\{x_2^3\} + E\{x_2^4\} - 3E\{x_1^2\}^2 - 12E\{x_1\}E\{x_1\}E\{x_2\} - 6E\{x_1^2\}E\{x_2^2\} - 12E\{x_1\}^2E\{x_2\}^2 - 12E\{x_1\}E\{x_2\}E\{x_2^2\} - 3E\{x_2^2\}^2.$$

Here, $E\{x_1\} = E\{x_2\} = 0$, so the above reduces to

$$kurt(x_1 + x_2) = E\{x_1^4\} + 6E\{x_1^2\}E\{x_2^2\} + E\{x_2^4\} - 3E\{x_1^2\}^2 - 6E\{x_1^2\}E\{x_2^2\} - 3E\{x_2^2\}^2.$$

The terms $6E\{x_1^2\}E\{x_2^2\}$ and $-6E\{x_1^2\}E\{x_2^2\}$ cancel each other. Rearranging terms, we get

$$kurt(x_1 + x_2) = E\{x_1^4\} - 3E\{x_1^2\}^2 + E\{x_2^4\} - 3E\{x_2^2\}^2 = kurt(x_1) + kurt(x_2)$$

Let us prove the second property $kurt(\alpha x_1) = \alpha^4 kurt(x_1)$. We have

$$kurt(\alpha x_1) = E\{(\alpha x_1)^4\} - 3(E\{(\alpha x_1)^2\})^2 = E\{\alpha^4 x_1^4\} - 3(E\{\alpha^2 x_1^2\})^2$$
$$= \alpha^4 E\{x_1^4\} - 3(\alpha^2 E\{x_1^2\})^2 = \alpha^4 E\{x_1^4\} - 3\alpha^4 (E\{x_1^2\})^2$$
$$= \alpha^4 (E\{x_1^4\} - 3(E\{x_1^2\})^2) = \alpha^4 kurt(x_1).$$

4. Let \mathbf{x} be the observed vector, and denote

$$\mathbf{x}_2 = \mathbf{E} \mathbf{D}^{-1/2} \mathbf{E}^T \mathbf{x}_2$$

where **E** is the orthogonal matrix of eigenvectors of $E\{\mathbf{x}\mathbf{x}^T\}$, **D** is the diagonal matrix of its eigenvalues, $\mathbf{D} = \text{diag}(d_1, \ldots, d_n)$, and $\mathbf{D}^{-1/2}$ is a diagonal matrix whose diagonal elements are simply those of **D** raised to power -1/2, $\mathbf{D} = \text{diag}(d_1^{-1/2}, \ldots, d_n^{-1/2})$. Let us show that \mathbf{x}_2 is white.

Assume that **x** is zero-mean $(E\{\mathbf{x}\} = \mathbf{0})$. The matrices **E** and **D** are constant with regard to the expectation operator. Then

$$E\{\mathbf{x}_2\} = E\{\mathbf{E}\mathbf{D}^{-1/2}\mathbf{E}^T\mathbf{x}\} = \mathbf{E}\mathbf{D}^{-1/2}\mathbf{E}^T E\{\mathbf{x}\} = \mathbf{E}\mathbf{D}^{-1/2}\mathbf{E}^T\mathbf{0} = \mathbf{0}$$

It remains to show that $E\{\mathbf{x}_2\mathbf{x}_2^T\} = \mathbf{I}$. We have

$$E\{\mathbf{x}_{2}\mathbf{x}_{2}^{T}\} = E\{(\mathbf{E}\mathbf{D}^{-1/2}\mathbf{E}^{T}\mathbf{x})(\mathbf{E}\mathbf{D}^{-1/2}\mathbf{E}^{T}\mathbf{x})^{T}\} = E\{\mathbf{E}\mathbf{D}^{-1/2}\mathbf{E}^{T}\mathbf{x}\mathbf{x}^{T}\mathbf{E}\mathbf{D}^{T-1/2}\mathbf{E}^{T}\}$$
$$= \mathbf{E}\mathbf{D}^{-1/2}\mathbf{E}^{T}E\{\mathbf{x}\mathbf{x}^{T}\}\mathbf{E}\mathbf{D}^{T-1/2}\mathbf{E}^{T},$$

where the last equality follows because \mathbf{E} and \mathbf{D} are constant with regard to expectation. From the definition of \mathbf{E} and \mathbf{D} we have the eigendecomposition

$$E\{\mathbf{x}\mathbf{x}^T\} = \mathbf{E}\mathbf{D}\mathbf{E}^T.$$

Inserting this into the previous equation we get

$$E\{\mathbf{x}_2\mathbf{x}_2^T\} = \mathbf{E}\mathbf{D}^{-1/2}\mathbf{E}^T(\mathbf{E}\mathbf{D}\mathbf{E}^T)\mathbf{E}\mathbf{D}^{T-1/2}\mathbf{E}^T$$

Since the eigenvector matrix **E** is orthogonal, we have $\mathbf{E}^T \mathbf{E} = \mathbf{E} \mathbf{E}^T = \mathbf{I}$. Applying this, we get

$$E\{\mathbf{x}_{2}\mathbf{x}_{2}^{T}\} = \mathbf{E}\mathbf{D}^{-1/2}(\mathbf{E}^{T}\mathbf{E})\mathbf{D}(\mathbf{E}^{T}\mathbf{E})\mathbf{D}^{T-1/2}\mathbf{E}^{T}$$
$$= \mathbf{E}\mathbf{D}^{-1/2}\mathbf{I}\mathbf{D}\mathbf{I}\mathbf{D}^{T-1/2}\mathbf{E}^{T} = \mathbf{E}(\mathbf{D}^{-1/2}\mathbf{D}\mathbf{D}^{T-1/2})\mathbf{E}^{T}$$
$$= \mathbf{E}(\operatorname{diag}(d_{1}^{-1/2}, \dots, d_{n}^{-1/2})\operatorname{diag}(d_{1}, \dots, d_{n})\operatorname{diag}(d_{1}^{-1/2}, \dots, d_{n}^{-1/2}))\mathbf{E}^{T}$$
$$= \mathbf{E}(\operatorname{diag}(d_{1}^{-1/2}, \dots, d_{n}^{-1/2})\operatorname{diag}(d_{1}^{1/2}, \dots, d_{n}^{1/2}))\mathbf{E}^{T}$$
$$= \mathbf{E}\mathbf{I}\mathbf{E}^{T} = \mathbf{E}\mathbf{E}^{T} = \mathbf{I}.$$

Therefore \mathbf{x}_2 is white.

5. Let us consider the distribution

$$g(x) = \frac{b}{4} \{ \exp(-b|x-a|) + \exp(-b|x+a|) \}$$

where we assume b > 0 (otherwise g(x) would not be a distribution).

(a) The n^{th} order moment of a distribution p(x) with infinite support is

$$m_n = \int_{-\infty}^{\infty} p(x) x^n dx.$$

Note that g(x) is symmetric about zero. Therefore the mean (first moment) of the distribution is zero (this can also be proved by integration). The kurtosis of g(x) (the kurtosis of a random variable x distributed according to g(x)) is then defined by

$$kurt_{g(x)}(x) = E\{x^4\} - 3(E\{x^2\})^2 = m_4 - 3m_2^2.$$

Let us calculate m_4 and m_2 . For m_n we have

$$m_n = \int_{-\infty}^{\infty} g(x)x^n dx = \frac{b}{4} \int_{-\infty}^{\infty} \{\exp(-b|x-a|) + \exp(-b|x+a|)\} x^n dx$$
$$= \frac{b}{4} \int_{-\infty}^{\infty} \exp(-b|x-a|)x^n dx + \frac{b}{4} \int_{-\infty}^{\infty} \exp(-b|x+a|)x^n dx$$

$$= \frac{b}{4} \left[\int_{-\infty}^{a} e^{b(x-a)} x^{n} dx + \int_{a}^{\infty} e^{-b(x-a)} x^{n} dx + \int_{-\infty}^{-a} e^{b(x+a)} x^{n} dx + \int_{-a}^{\infty} e^{-b(x+a)} x^{n} dx \right]$$

$$= \frac{b}{4} \left[e^{-ba} \int_{-\infty}^{a} e^{bx} x^{n} dx + e^{ba} \int_{a}^{\infty} e^{-bx} x^{n} dx + e^{ba} \int_{-\infty}^{-a} e^{bx} x^{n} dx + e^{-ba} \int_{-a}^{\infty} e^{-bx} x^{n} dx \right]$$

In our case, *n* is even so x^{n} is symmetric about zero. Let us then change the

In our case, n is even, so x^n is symmetric about zero. Let us then change the integration variable from x to -x in the second and fourth integrals. We get

$$m_{n} = \frac{b}{4} \left[e^{-ba} \int_{-\infty}^{a} e^{bx} x^{n} dx - e^{ba} \int_{-a}^{-\infty} e^{bx} x^{n} dx + e^{ba} \int_{-\infty}^{-a} e^{bx} x^{n} dx - e^{-ba} \int_{a}^{-\infty} e^{bx} x^{n} dx \right]$$
$$= \frac{b}{4} \left[e^{-ba} \int_{-\infty}^{a} e^{bx} x^{n} dx + e^{ba} \int_{-\infty}^{-a} e^{bx} x^{n} dx + e^{ba} \int_{-\infty}^{-a} e^{bx} x^{n} dx + e^{-ba} \int_{-\infty}^{a} e^{bx} x^{n} dx \right]$$
$$= \frac{b}{2} \left[e^{-ba} \int_{-\infty}^{a} e^{bx} x^{n} dx + e^{ba} \int_{-\infty}^{-a} e^{bx} x^{n} dx \right].$$

The remaining integrals can be computed by partial integration. For n = 4 we have

$$\int_{-\infty}^{c} e^{bx} x^{4} dx = \frac{c^{4}}{b} e^{bc} - \int_{-\infty}^{c} \frac{4}{b} e^{bx} x^{3} dx$$
$$= \left[\frac{c^{4}}{b} - \frac{4c^{3}}{b^{2}}\right] e^{bc} + \int_{-\infty}^{c} \frac{12}{b^{2}} e^{bx} x^{2} dx = \left[\frac{c^{4}}{b} - \frac{4c^{3}}{b^{2}} + \frac{12c^{2}}{b^{3}}\right] e^{bc} - \int_{-\infty}^{c} \frac{24}{b^{3}} e^{bx} x dx$$
$$= \left[\frac{c^{4}}{b} - \frac{4c^{3}}{b^{2}} + \frac{12c^{2}}{b^{3}} - \frac{24c}{b^{4}}\right] e^{bc} + \int_{-\infty}^{c} \frac{24}{b^{4}} e^{bx} dx = \left[\frac{c^{4}}{b} - \frac{4c^{3}}{b^{2}} + \frac{12c^{2}}{b^{3}} - \frac{24c}{b^{4}} + \frac{24}{b^{5}}\right] e^{bc}$$

Inserting this result into the formula for m_4 , with a and -a in place of c, respectively, we get

$$m_4 = \frac{b}{2}e^{-ba+ba} \left[\left(\frac{a^4}{b} - \frac{4a^3}{b^2} + \frac{12a^2}{b^3} - \frac{24a}{b^4} + \frac{24}{b^5} \right) + \left(\frac{a^4}{b} + \frac{4a^3}{b^2} + \frac{12a^2}{b^3} + \frac{24a}{b^4} + \frac{24}{b^5} \right) \right]$$
$$= b \left[\frac{a^4}{b} + \frac{12a^2}{b^3} + \frac{24}{b^5} \right].$$

Performing a similar partial integration procedure for m_2 , we get

$$m_2 = \frac{b}{2} \left[e^{-ba} e^{ba} \left(\frac{a^2}{b} - \frac{2a}{b^2} + \frac{2}{b^3} \right) + e^{ba} e^{-ba} \left(\frac{a^2}{b} + \frac{2a}{b^2} + \frac{2}{b^3} \right) \right] = b \left[\frac{a^2}{b} + \frac{2}{b^3} \right].$$

Inserting these results into the moment-based formula for the kurtosis, we have

$$kurt_{g(x)}(x) = m_4 - 3m_2^2 = b\left[\frac{a^4}{b} + \frac{12a^2}{b^3} + \frac{24}{b^5}\right] - 3b^2\left[\frac{a^4}{b^2} + \frac{4a^2}{b^4} + \frac{4}{b^6}\right] = \frac{12 - 2a^4b^4}{b^4}.$$

Let us assume that the distribution g(x) has unit variance $(m_2 = 1)$. Then

$$b\left[\frac{a^2}{b} + \frac{2}{b^3}\right] = a^2 + \frac{2}{b^2} = 1 \Rightarrow (a^2 + \frac{2}{b^2})^2 = a^4 + \frac{4a^2}{b^2} + \frac{4}{b^4} = 1$$
$$\Rightarrow b^4 = b^4 a^4 + 4a^2 b^2 + 4 \Rightarrow kurt_{g(x)}(x) = \frac{12 - 2a^4 b^4}{4 + 4a^2 b^2 + a^4 b^4}.$$

Here we require $b^2 > 0 \Rightarrow a^2 < 1$, where the the right-hand side follows from the unit variance assumption. In this case, the previous formula is in fact simpler.

- (b) Since $b^4 > 0$, the sign of the kurtosis depends only on the numerator term of the above expression.
 - i. When the kurtosis is negative, we have

$$12 - 2a^4b^4 < 0 \Rightarrow a^4 > \frac{6}{b^4} \Rightarrow a^2 > \frac{\sqrt{6}}{b^2} \Rightarrow |a| > \frac{\sqrt[4]{6}}{b}.$$

With the unit variance assumption, we have $b^4 = 4/(1 - 2a^2 + a^4)$, from which

$$\begin{aligned} a^4 > \frac{6}{b^4} &= \frac{3}{2}(1 - 2a^2 + a^4) \Rightarrow a^4 - 6a^2 + 3 < 0, a^2 > 0 \\ \Rightarrow 3 - \sqrt{6} < a^2 < 3 + \sqrt{6} \Rightarrow \sqrt{3 - \sqrt{6}} < |a| < \sqrt{3 + \sqrt{6}} \Rightarrow \sqrt{3 - \sqrt{6}} < |a| < 1 \; . \end{aligned}$$

The corresponding values for b can be calculated from the unit variance assumption (see the formula above).

- ii. The kurtosis is zero when $|a| = \sqrt[4]{6}/b$. In the unit variance case this becomes $|a| = \sqrt{3 \sqrt{6}}$ (2 points).
- iii. The kurtosis is positive when $|a| < \sqrt[4]{6}/b$. In the unit variance case this becomes $|a| < \sqrt{3 \sqrt{6}}$ (1 interval).
- (c) Distributions (or the associated random variables) with negative kurtosis are called subgaussian and distributions with positive kurtosis are called supergaussian. Here, the distribution g(x) can be either, depending on the values of a and b (see the previous section). In the figure below, the solid curve is subgaussian, the dashed curve has zero kurtosis and the dashdot curve is supergaussian.

