## T-61.5040 Oppivat mallit ja menetelmät

## T-61.5040 Learning Models and Methods

## Pajunen, Viitaniemi

## Solutions to exercise 5, 16.2.2007

## Problem 1.

i) Consider a set of $n=v$ observations $Z_{v}$. Then, by definition, the first of the formulas defining $v$ hold, $G(v)=v \log 2=\log 2^{v}$, i.e. $\max N\left(Z_{v}\right)=2^{v}$. That is, every possible dichotomy can be obtained using the given set of functions.
We can pick a subset of size $n$ from the above set of observations $Z_{v}$, and again all possible dichotomies can be obtained for this set of observations. Thus $G(n)=n \log 2$ when $n \leq v$.

In other words, linearity must hold for all $n$ in $[1, v]$, there cannot be $n$ for which the linearity does not hold. We can rewrite the definition of $G(n)$ :

$$
G(n)= \begin{cases}=n \log 2, & n \leq v \\ \leq v\left(\log \left(\frac{n}{v}\right)+1\right), & n>v\end{cases}
$$



Figure 1: Straight line: $n \log 2$. Curves: $v\left(\log \frac{n}{v}+1\right)$ where $v=10,50,100$ (from left to right).
ii)

$$
\begin{aligned}
\lim _{n \rightarrow \infty} \frac{G(n)}{n} & \leq \lim _{n \rightarrow \infty} \frac{v\left(\log \left(\frac{n}{v}\right)+1\right)}{n} \\
& =\lim _{n \rightarrow \infty} \frac{v}{n}(\log n-\log v+1) \\
& =\lim _{n \rightarrow \infty} \frac{v \log (n)}{n}-\frac{v \log v}{n}+\frac{v}{n} \\
& =\lim _{n \rightarrow \infty} \frac{v \log (n)}{n}
\end{aligned}
$$

Now use L'Hospital's rule: differentiate numerator and denominator separately with respect to $n$. We get

$$
\lim _{n \rightarrow \infty} \frac{v \log (n)}{n}=\lim _{n \rightarrow \infty} \frac{v}{n}=0
$$

and thus

$$
\lim _{n \rightarrow \infty} \frac{G(n)}{n}=0
$$

## Problem 2.

i) There are $2^{n-1}$ different vectors and $2^{n-1}-m$ are outside the training set. Since we don't know the last bits for the off-training set vectors, the expected contribution to the average error is $1 / 2\left[\frac{2^{n-1}-m}{2^{n-1}}\right]$. Since the training error is $s$, its contribution to the average error is $m s / 2^{n-1}$. So the average error is their sum

$$
c=\left[2^{n-2}+(s-1 / 2) m\right] / 2^{n-1} .
$$

If $m$ is small and/or $s$ is close to $1 / 2$, the average error is close to $1 / 2$. The only reason that the average error is not $1 / 2$ is that the average error considers also the training set. If training data is well classified $(s<1 / 2)$, then the average error is also slightly less than $1 / 2$. Off-training set error is always $1 / 2$

Comments: note that this result seems to contradict SLT bounds. But considering the situation carefully, we note that we are not averaging over all possible training sets of size $m$. We have a given training set and conditional to that training set, the function $h$ cannot generalize outside the training set. This is not surprising when considering the No Free Lunch theorems. Off-training set error is independent of the training error if we average uniformly over all problems.
ii) Denote by $N$ the number of binary vectors incorrectly classified by $h$. Then $c=N / 2^{n-1}$. The training error $s$ is the number of such vectors picked in the training set, divided by $m$.

The inequality $|c-s| \leq \epsilon$ is equivalent to $|c-z / m| \leq \epsilon$ where $z=s m$.
We are going to use the Hoeffding inequality:

If $x_{1}, \ldots, x_{n}$ are iid random variables for which $x_{i}-E\left(x_{i}\right) \in\left[a_{i}, b_{i}\right]$ and $X=\sum_{i} x_{i}$, then

$$
p(X-E(X) \geq \epsilon) \leq \exp \left(-2 \epsilon^{2} / \sum_{i}\left(b_{i}-a_{i}\right)^{2}\right) .
$$

Write $c-s=\sum_{i=1}^{m}\left(c-z_{i}\right) / m$ where $z_{i}$ denotes the classification error at point $x_{i}$. Then $z_{i}$ is Bernoulli distributed with parameter $c$. Now look at $p(c-s \geq \epsilon)$. Hoeffding inequality applies for $(c-s)$ with $E(c-s)=\sum E\left(c-z_{i}\right) / m=0$. As $\left(c-z_{i}\right) / m \in[(c-1) / m, c / m]$, $\left(b_{i}-a_{i}\right)^{2}=1 / m^{2}$ and we get

$$
p(c-s \geq \epsilon) \leq \exp \left(-2 m \epsilon^{2}\right)
$$

Changing signs we get

$$
p(c-s \leq-\epsilon) \leq \exp \left(-2 m \epsilon^{2}\right),
$$

So

$$
p(|c-s| \geq \epsilon) \leq 2 \exp \left(-2 m \epsilon^{2}\right)
$$

Comments: this result explicitly shows what the SLT bound means. It examines the distribution of training errors $s$ around their mean $c$. There is a binomial distribution behind this: randomly picking training points result in random errors and the sum of errors is tightly clustered around $c$. That is why it is unlikely that $c$ and $s$ are very far from each other, taken over all training sets.

## Problem 3.

i) A reasonable prior would be such that $n c$ has a binomial distribution $\operatorname{Bin}(n, 1 / 2)$. If we choose $h$ independent of the problem, each prediction it makes is equally likely to be or right or wrong. We furthermore assume that the prediction errors are independent, which leads to a binomial distribution.
ii) Probability of winning at least seven times is $p(c \leq 0.3)$. For a constant prior this is $4 / 11$. The expected winnings are then $4 / 11 * 10000-2500 \approx 1136>0$. Relying on a constant prior, you should take the deal.

The casino manager does not use a constant prior since he is still in business. He assumes that each outcome is independent of the others, and red/black are equally probable. Then $p(c \leq 0.3)=p(c=0)+p(c=0.1)+p(c=0.2)+p(c=0.3)=2^{-10}(1+10+90 / 2+720 / 6)=$ $176 / 1024 \approx 0.17$.

The expected winnings for the casino are $\mathrm{E}(-C)=2500-10000 * 0.17=300$

## Problem 4.

We consider the conditional density $p(c \mid s, h, m)$. We will compare the values of this for $c=0.1$ and $c=0.5$. Use Bayes' Theorem to write

$$
p(c \mid s, h, m) \propto p(s \mid c, h, m) p(c \mid h, m) .
$$

On the right-hand side, the likelihood $p(s \mid c, h, m)$ is obtained by considering $m$ random points when the average error is $c$. The product $s m$ has a binomial distribution $\operatorname{Bin}(m, c)$.
The new probability $p(c \mid h, m)$ is literally "what do we know about $c$ when all we assume is $h$ and $m$ ?" $c$ is determined by the true function $f$, which we don't know, and is not affected by $m$. All we can assume is that our function $h$ guesses correctly as often as not. We also assume that the guessing errors are independent. Therefore $n c$ has a binomial distribution $\operatorname{Bin}(n, 1 / 2)$.

Suppose $s=0.1, n=1000$, and $m=100$. What is the posterior when $c=0.1=s$ and $c=0.5$ ? These points are selected since they maximize the first and the second probability in the posterior correspondingly. The first probability $p(s \mid c, h, m)$ is

$$
\begin{equation*}
\binom{m}{s m} c^{s m}(1-c)^{m-s m} \tag{1}
\end{equation*}
$$

and the second probability $p(c \mid h, m)$ is

$$
\begin{equation*}
\binom{n}{c n} 2^{-n} \tag{2}
\end{equation*}
$$

Setting $c=0.1=s,(1)$ gives $\binom{100}{10}(0.1)^{10}(0.9)^{90}$ and $(2)$ gives $\binom{1000}{100} 2^{-1000}$.
When $c=0.5$, (1) gives $\binom{100}{10} 2^{-100}$ and (2) gives $\binom{1000}{500} 2^{-1000}$.
Compute the ratio $p(c=0.1 \mid s, h, m) / p(c=0.5 \mid s, h, m)$ to obtain

$$
(0.1)^{10}(0.9)^{90} 2^{100} \frac{\prod_{i=101}^{500} i}{\prod_{j=501}^{900} j} .
$$

The dominating term is the last ratio of products which is very small. Numerically, the whole ratio is about $2 * 10^{-144}$. This shows that the posterior probability is significantly higher at $c=0.5$.

Comments: Despite SLT bounds, we can't conclude that small $s$ implies small $c$ unless we are willing to make strong assumptions about the true model $f$ (and therefore about $p(c \mid h))$.

