# T-61.5040 Oppivat mallit ja menetelmät T-61.5040 Learning Models and Methods Pajunen, Viitaniemi

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## Problem 1.

In variational learning the following expression is maximised:

$$C = \int q(\theta) \log\left(\frac{p(y|\theta)p(\theta)}{q(\theta)}\right) d\theta$$

i) Justify variational learning by showing that it minimizes the Kullback-Leibler divergence D(q||p) between  $q(\theta)$  and  $p(\theta|y)$ .

ii) The evidence p(y), or the prior predictive distribution, is the probability of the data according to the model  $p(y, \theta)$ . The evidence can not be computed if the model can not be integrated. Show that maximising C maximises a lower bound for p(y). Hint: Jensen's inequality for a random variable X and a convex function  $f: E[f(X)] \ge f(E[X])$ .

## Problem 2.

Consider what happens in variational learning with a Normal approximate posterior  $q(\theta)$ , when the true posterior  $p(\theta|y)$  is a mixture of two Normal distributions  $N(\theta|\mu_i, \sigma_i^2)$ , i = 1, 2with prior probabilities  $a_1$  and  $a_2 = 1 - a_1$ . Assume that the mixture distributions  $N(\theta|\mu_i, \sigma_i^2)$ are separated well enough to warrant fitting q separately to the mixture components.

## Problem 3.

The Poisson distribution with intensity  $\lambda$  is

$$p(k|\lambda) = e^{-\lambda} \frac{\lambda^k}{k!}$$

i) Compute the Laplace approximation for  $p(\lambda|k)$  using the prior  $p(\lambda) \propto \lambda^{-1}$ .

ii) Also compute the Laplace approximation for  $p(\log \lambda | k)$ . Note that the prior is now  $p(\log \lambda) \propto 1$  (This follows from the formula for the density of a transformation: Let  $l = g(\lambda) = \log \lambda$ . Now  $p_l(l) = (\frac{\partial g(\lambda)}{\partial \lambda})^{-1} \cdot p_{\lambda}(\lambda)$ .)

# Problem 4.

Approximate the posterior  $p(\theta|y)$  by another distribution  $q(\theta)$ . Use  $q(\theta) = N(\theta|\theta_0, \sigma^2)$  where the variance  $\sigma^2$  is known. What is  $\theta_0$  when

- i) you minimize the KL divergence  $D(p(\theta|y)||q(\theta))$ ?
- ii) you minimize the KL divergence  $D(q(\theta)||p(\theta|y))$ ?

Note that in part ii), the solution can be found only approximately.