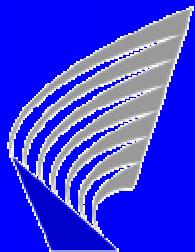


Input and Variable Selection for Local Models

Antti Sorjamaa



Outline

- | Basic Concepts
- | Input selection
- | Models
 - k -NN, Lazy Learning
- | Variable Selection
 - Leave-one-out, Bootstraps
- | Results



Selection – The Word of Today

| Inputs

- Input selection method (Wrapper or Filter)

| Model

| Parameters

- Validation method
- Bounds

| Local or Global

| Data sets

- Learning, validation, test



Selection Principle

$$\mathbf{x}_n \in R^d, y_t \in R$$

| Notations:

$$\hat{y}_n = g(\mathbf{x}_n, q)$$

$$E_{\text{training}, \text{validation}}$$

| Generalization Error

$$E_{\text{gen}}(q) = \lim_{N \rightarrow \infty} \sum_{n=1}^N \frac{(g(\mathbf{x}_n, q) - y_n)^2}{N} \longrightarrow \boxed{\hat{E}_{\text{gen}}(q)}$$



to minimize



Input Selection

I Exhaustive method

- “Brute force”
- All 2^d input combinations explored

I Forward or Backward

- Only $d(d-1)$ input sets evaluated
- Local minima problems \rightarrow Suboptimal

I Forward-Backward

- “More Optimal” ∇ More input sets estimated
- Time consumption unknown beforehand



Input Selection (2)

- I Input selection with Forward-Backward method
 - Initialization

Possible Action	1	2	3	4	5
Initial	x	x			x
1		x			x
2	x				x
3	x	x	x		x
4	x	x		x	x
5	x	x			



k-NN

- | Fast and reliable
- | Can be used as a part or as a whole approximator
- | Can be used with many different methods
- | Only inputs and k need to be determined beforehand



k-NN

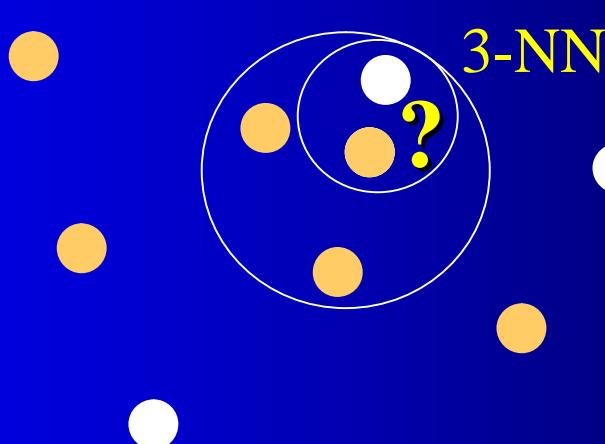
For Classification:



Class 1 Class 2

For Regression:

$$\hat{y}_i = \frac{\sum_{j=1}^k y_{P(j)}}{k}$$

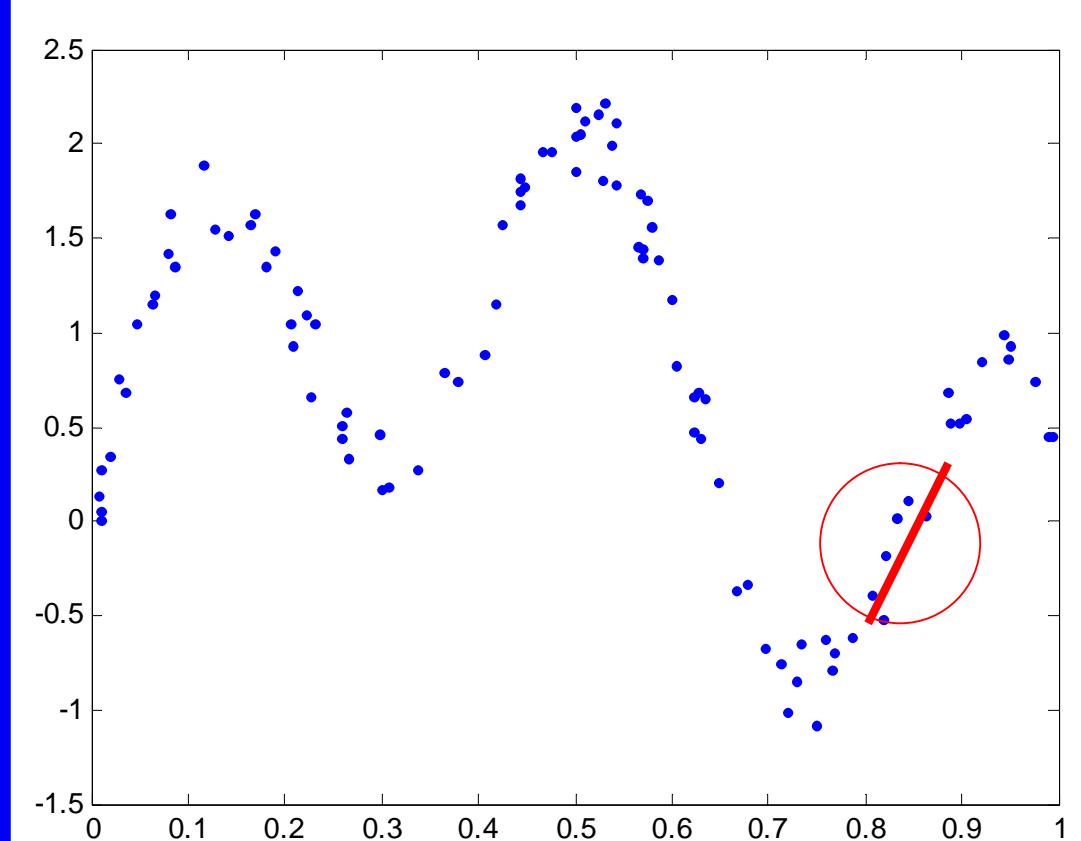


Lazy Learning

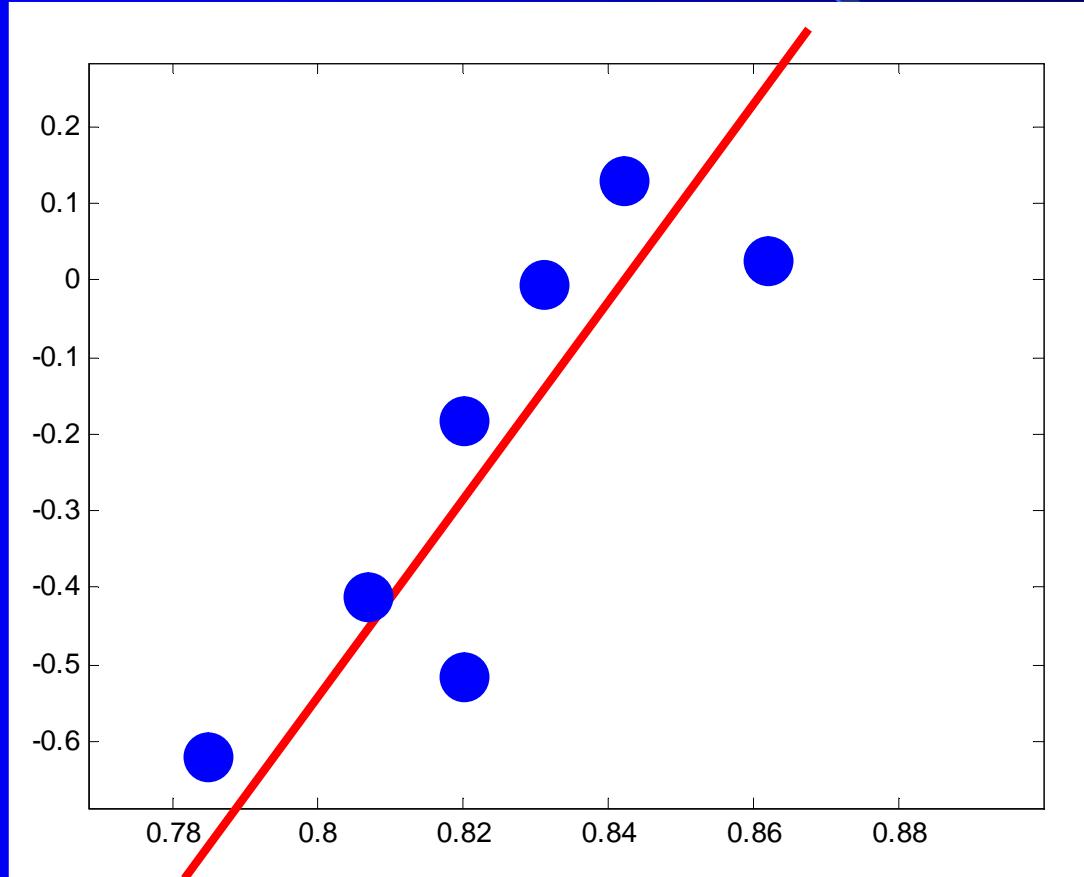
- | Local, linear model
- | Laziness
 - "Do nothing until query"
 - No learning mandatory
- | Compared to k -NN (local, constant model)
 - More time consuming than k -NN
 - Almost as diversified
- | Locality can be "globalized" incrementally



Local, linear model



Local, linear model



Formula

$$y_i = f(\mathbf{x}_i) + e_i$$

$$\sum_{i=1}^N \{(y_i - \mathbf{x}'_i \boldsymbol{\beta})^2 K\left(\frac{d(\mathbf{x}_i, \mathbf{x}_q)}{h}\right)\}$$



Formula

$$\sum_{i=1}^N \{(y_i - \mathbf{x}'_i \hat{\beta})^2 K\left(\frac{d(\mathbf{x}_i, \mathbf{x}_q)}{h}\right)\}$$

Simplified version: K à KNN

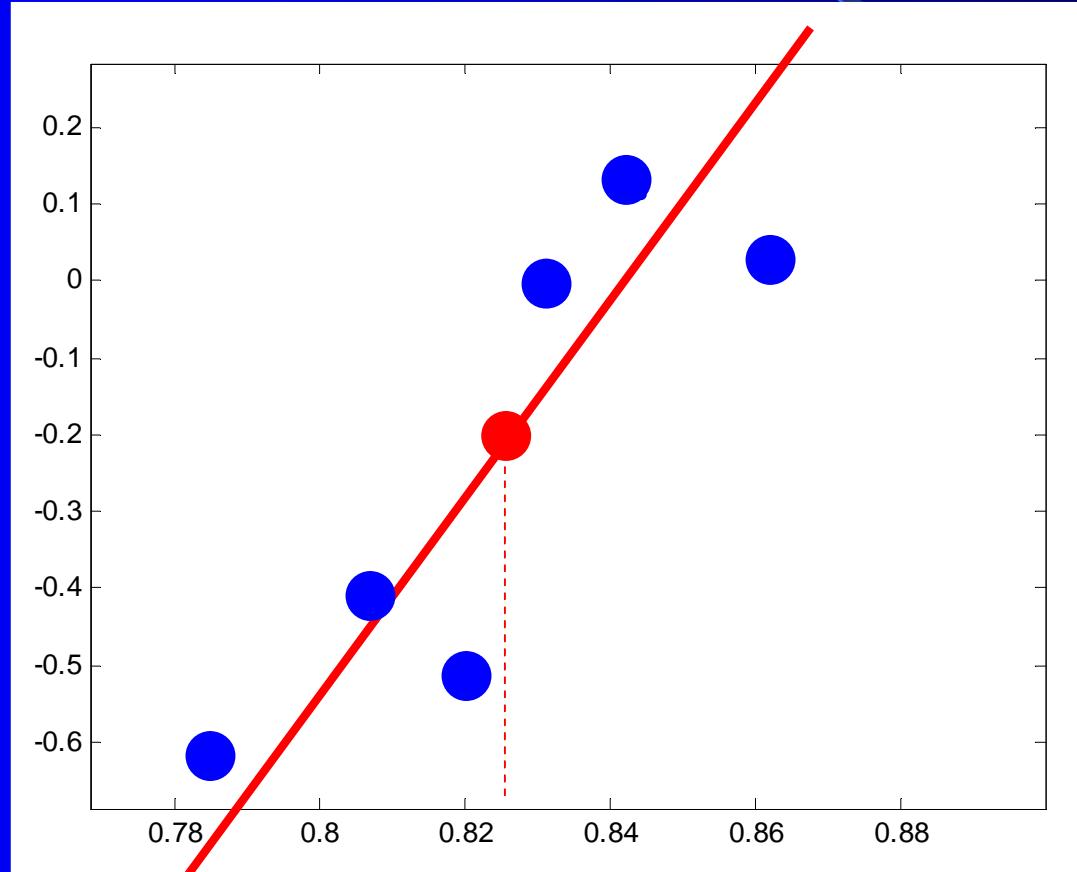
$$\mathbf{P} = (\mathbf{X}' \mathbf{X})^{-1}$$

$$\hat{\beta} = \mathbf{P} \mathbf{X}' \mathbf{y}$$

$$\hat{y}_q = \mathbf{x}'_q \hat{\beta}$$



“Do nothing until query”



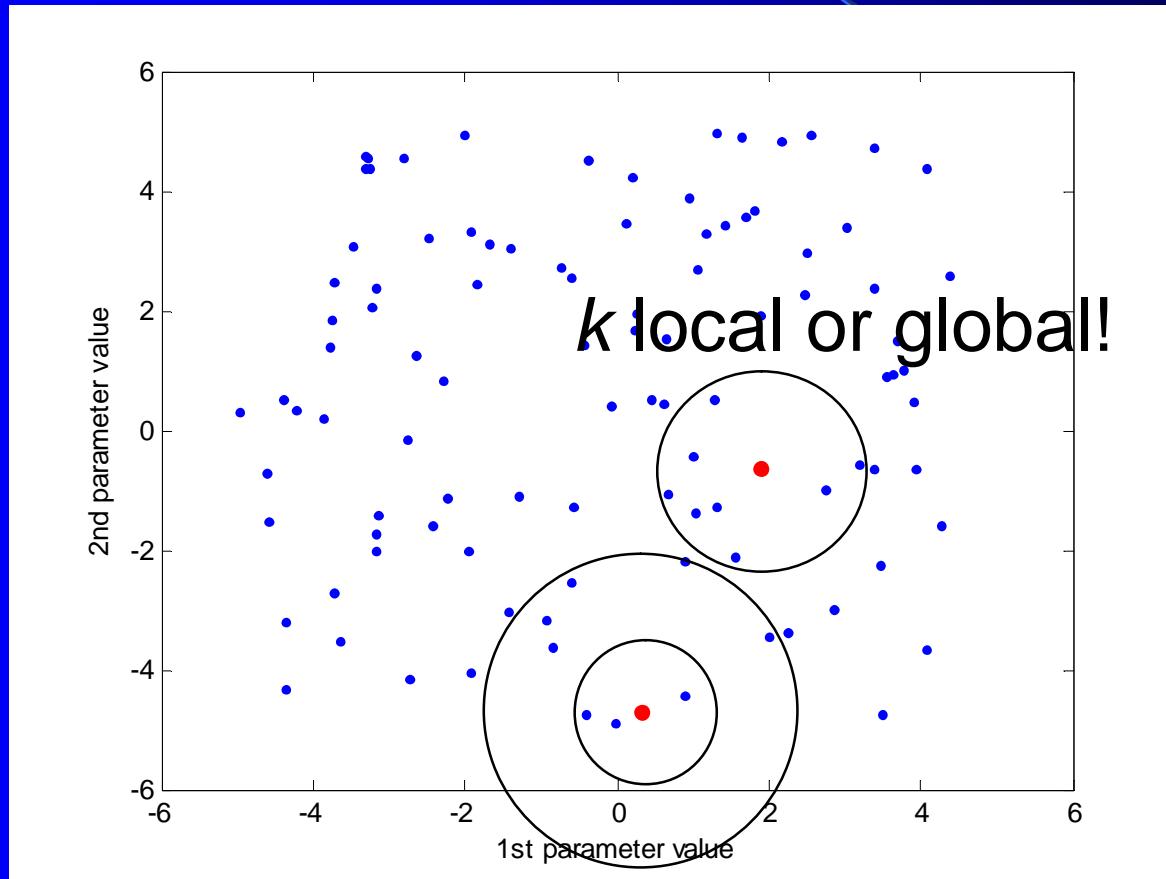
“Do nothing until query”

New input needs an output approximation

- | Validate optimal inputs
 - Search nearest neighbors
 - Validate optimal neighborhood size
 - | Build linear model
- | Calculate the needed estimate



Example: $y(t)=\text{LL}(y(t-1), y(t-2))$

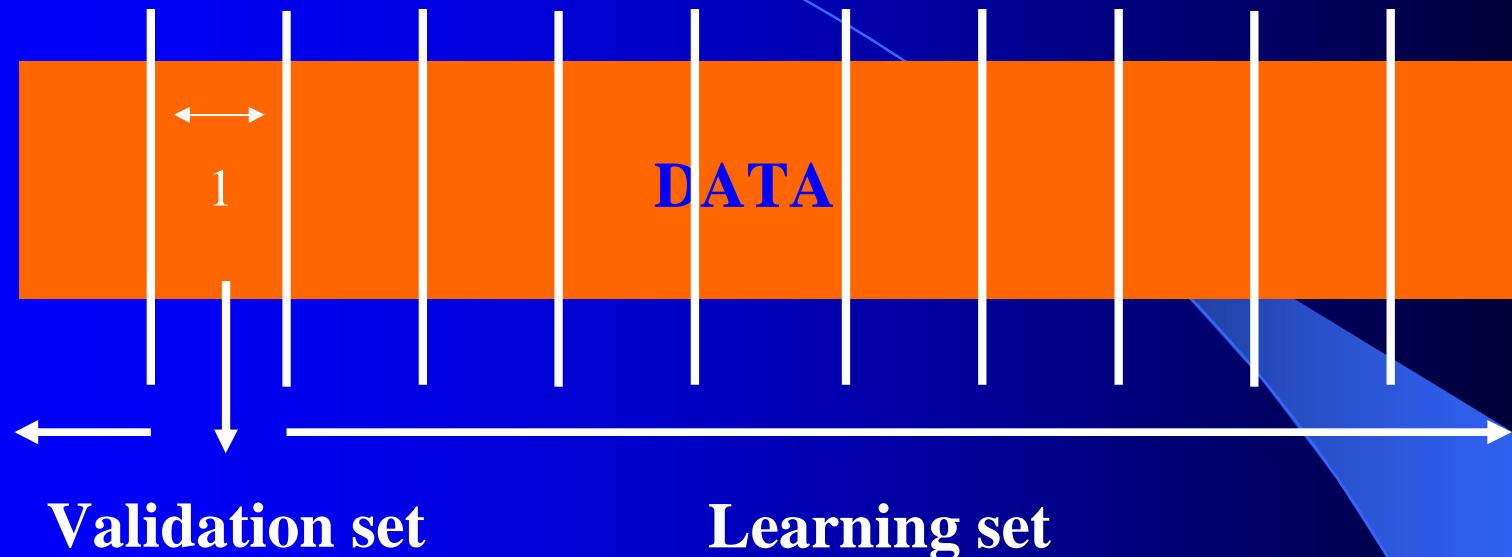


Lazy Learning

- | Locality can be "globalized" incrementally
 - Global k instead of Local k
 - Globally selected inputs instead of Local
- | More Globalization à Less Laziness
- | Best amount of Globalization should be determined for each case
 - Intensive validation and testing
 - Different attached methods



Leave-One-Out (LOO)



Validation set

Learning set

Error

A model is built

Procedure repeated **N** times

$$\hat{E}_{gen} = \frac{1}{N} \sum_{i=1}^N (\hat{y}_i - y_i)^2$$



Recursive formula for LOO

$$\mathbf{P}(k+1) = \mathbf{P}(k) - \frac{\mathbf{P}(k)\mathbf{x}(k+1)\mathbf{x}'(k+1)\mathbf{P}(k)}{1 + \mathbf{x}'(k+1)\mathbf{P}(k)\mathbf{x}(k+1)}$$

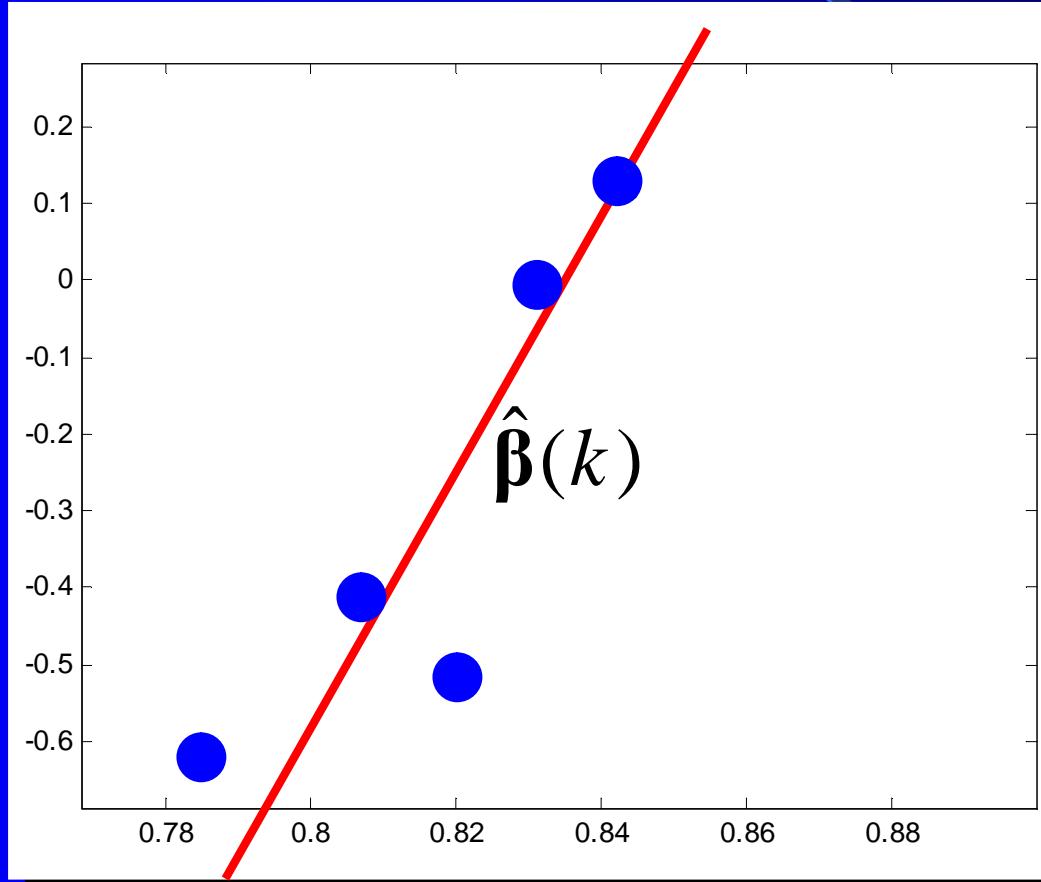
$$g(k+1) = \mathbf{P}(k+1)\mathbf{x}(k+1)$$

$$e(k+1) = y(k+1) - \mathbf{x}'(k+1)\hat{\beta}(k)$$

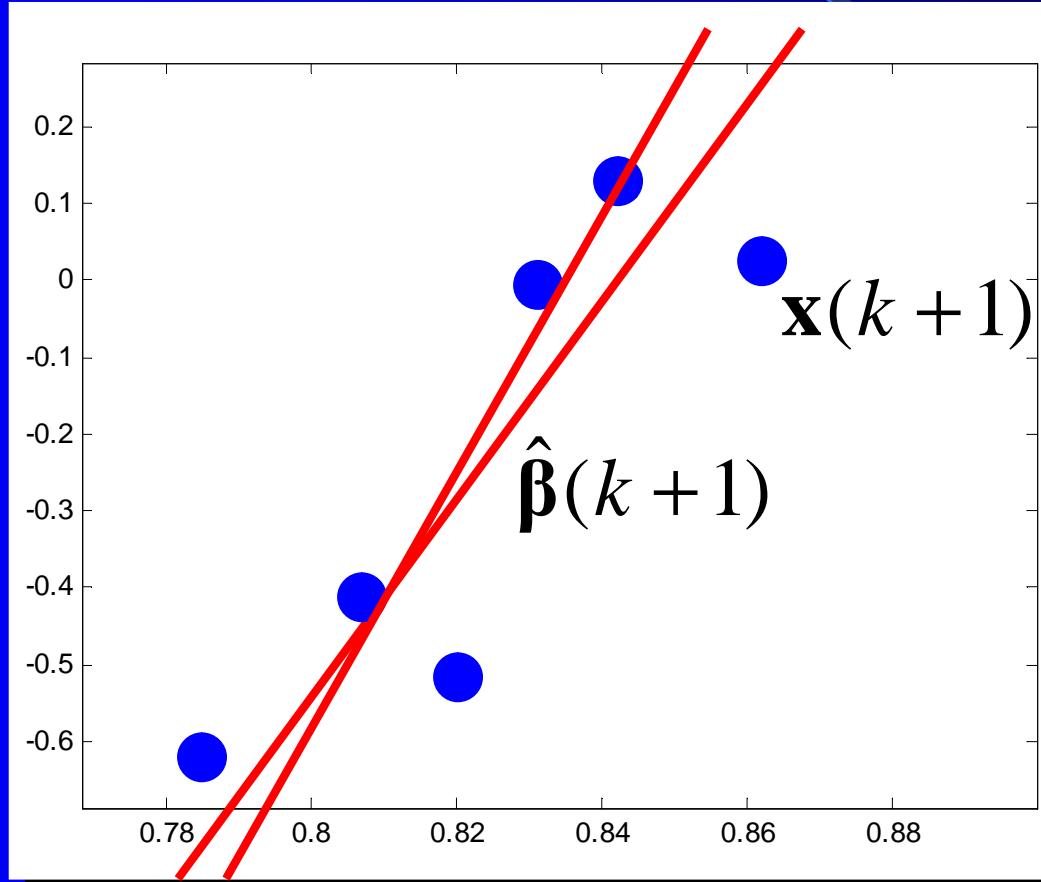
$$\hat{\beta}(k+1) = \hat{\beta}(k) + g(k+1)e(k+1)$$



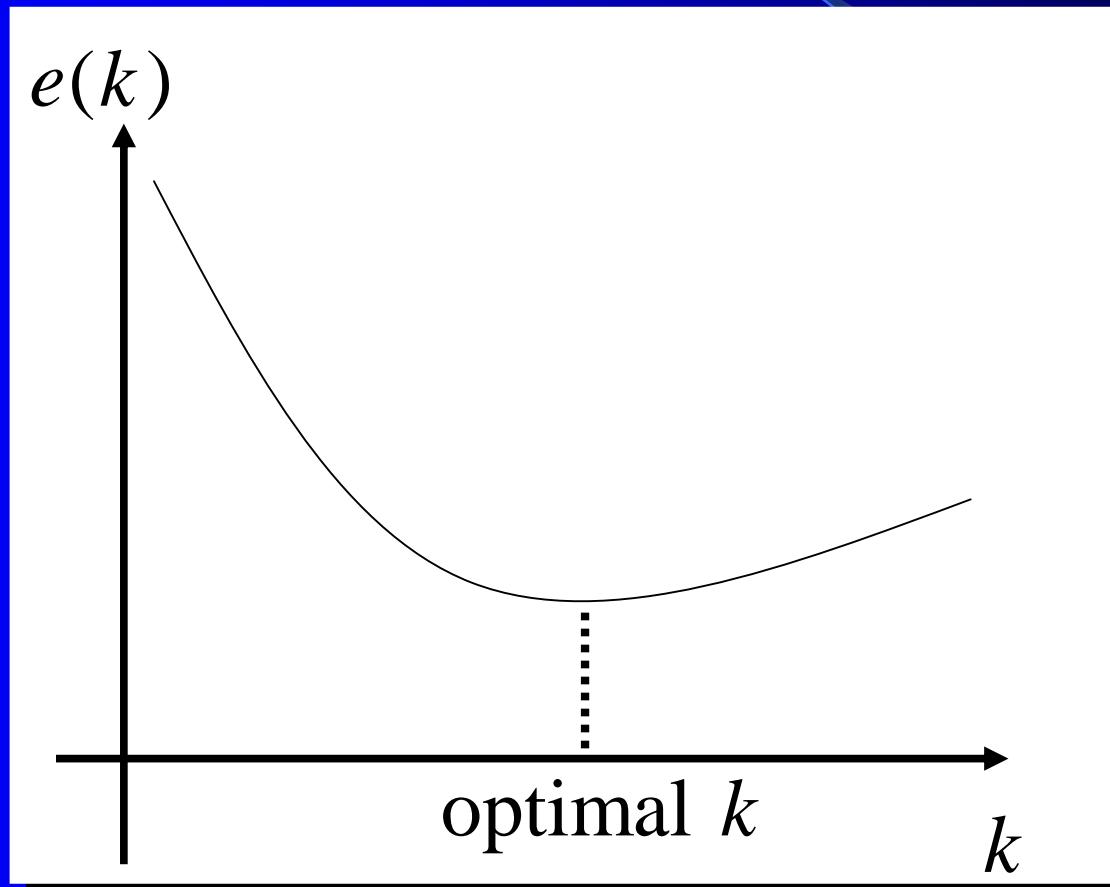
Recursive formula for LOO



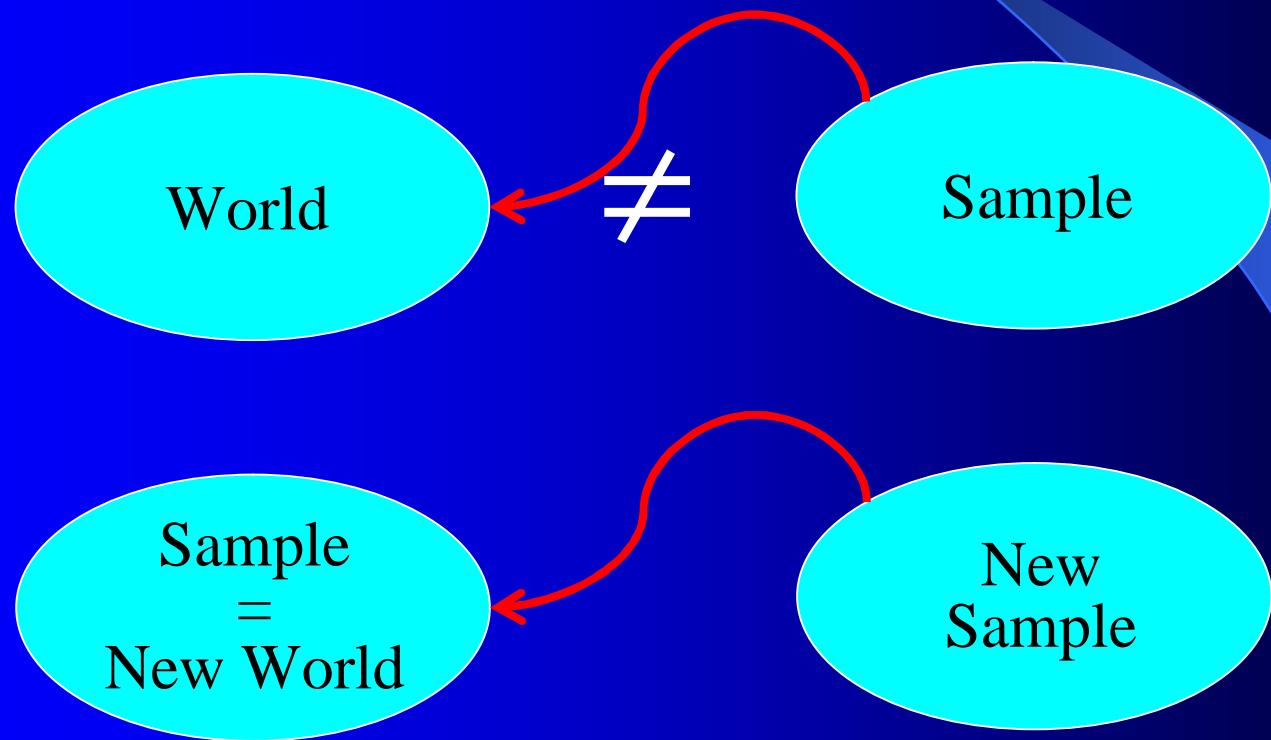
Recursive formula for LOO



Recursive formula for LOO



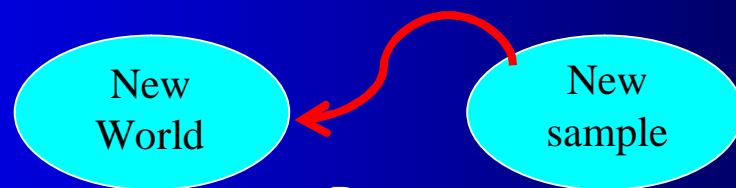
Bootstrap Resampling



Bootstrap Resampling

Definition: $\text{optimism}(q) \triangleq E_{sam,gen}(q) - E_{sam,sam}(q)$

$$E_{sam,gen}(q) = E_{sam,sam}(q) + \text{optimism}(q)$$



Estimate: $\hat{\text{optimism}}(q) = \frac{1}{B} \sum_{b=1}^B (E_{new,sam}^b(q) - E_{new,new}^b(q))$

$$\hat{E}_{sam,gen}(q) = E_{sam,sam}(q) + \hat{\text{optimism}}(q)$$



Bootstrap 632

Bootstrap:

$$\text{optimism}(q) = \frac{1}{B} \sum_{b=1}^B (\bar{E}_{new,sam}^b(q) - \bar{E}_{new,new}^b(q))$$

Bootstrap 632: $\text{optimism}^{632}(q) = \frac{1}{B} \sum_{b=1}^B (\bar{E}_{new,new}^b(q))$

$new = sample - new$

$$\hat{E}_{gen} = (1 - 0.632) E_{sam,sam} + 0.632 \text{optimism}^{632}(q)$$

- + 0.632 is derived from probability of single data point to be selected to bootstrap set
- + Unbiased and faster to evaluate



The Method

- | Input selection with brute force
 - All 2^d input combinations explored
- | Using k -NN as approximator
- | k selected with Leave-one-out, Bootstrap and Bootstrap 632
 - Best k selected with each method
- | Best input combination selected with each method



Results

- I Darwin Sea Pressure Data – 1400 values
 - 1000 values for training and 400 for testing

	Selected Inputs	k	\hat{E}_{gen}	Test error
LOO	$t - \{1, 2, 3, 5, 7, 8\}$	15	0.9219	1.1650
Bootstrap	$t - \{1, 2, 4, 5, 7, 8\}$	1	0.6054	1.8458
Bootstrap 632	$t - \{1, 2, 3, 5, 7, 8\}$	16	0.9333	1.1625



The Method²

- | Input selection
 - For k-NN, all 2^d input possibilities explored
 - For LL, Backward Selection and continuous
- | k selected with Leave-one-out
 - Best k selected with each method combination
- | Best input combination selected with each method combination
- | Testing k -NN selected inputs with LL



Results²

- I Santa Fe Data – 10 000 values
 - 1000 values for training and 9000 for testing

Method	Learning		Calculation time	Test	Prediction 40 steps
	k	LOO error	Minutes	MSE	MSE
LL	56	42.32	2.58	42.0746	1765.6
LL pruned	59	19.42	13.95	20.6037	148.37
k -NN	3	57.71	33.78	53.5387	1252.1
k -NN + LL	15	33.57	0.20	31.4548	1770.1



Conclusions

- | Leave-one-out is fast and good method to select inputs
- | Bootstraps can select more optimal number of neighbours for k -NN
- | Inputs selected with k -NN are not as good to use with LL than the ones selected with LL
 à k -NN is not good filter for LL



Questions?

Publications:

- | A. Sorjamaa, A. Lendasse, and M. Verleysen, "Pruned Lazy Learning Models for Time Series Prediction," pp. 509–514, ESANN 2005.
- | A. Sorjamaa, N. Reyhani, and A. Lendasse, "Input and Structure Selection for k -NN Approximator," in Lecture Notes in Computer Science, vol. 3512, pp. 985–991, IWANN 2005.
- | Chris Atkeson, A. Moore and S. Schaal. Locally weighted learning, AI Review, 11:11-73, April 1997

