

Evidence and Occam's razor

Based on David J.C. MacKay: Information Theory and Learning Algorithms, chapters 24,27, and 28

Arto Klami

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Contents

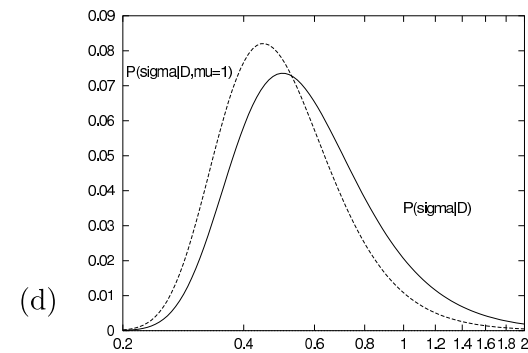
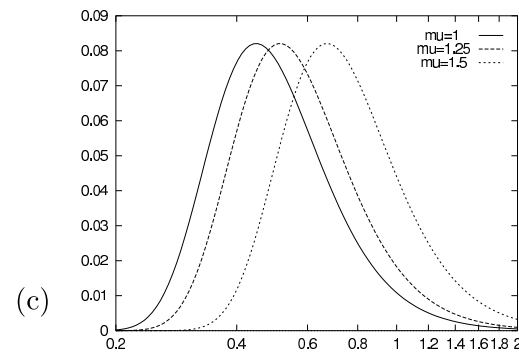
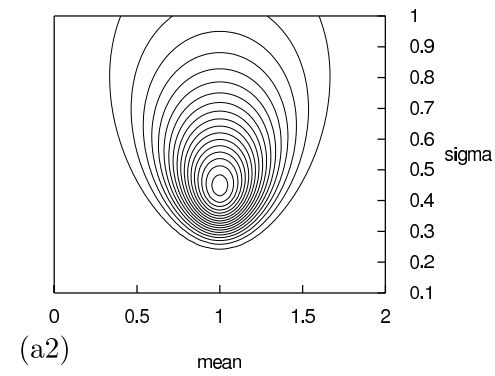
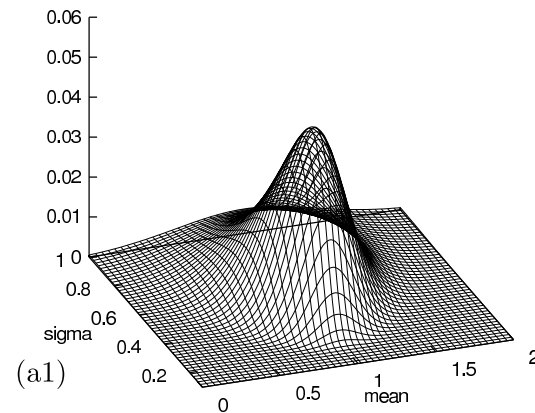
- Tools:
 - Exact marginalization
 - Laplace's approximation
- Occam's razor:
 - Idea
 - Two stages of modeling
 - Evidence and Occam factor
 - Minimum Description Length (MDL)
 - Connection to cross-validation

Exact marginalization

$$p(x|H) = \int p(x, y|H) dy$$

- “..is a macho activity enjoyed by those who are fluent in definite integration” (MacKay)
- The concept is necessary:
 $p(x|H)$ is not the same as $p(x|\hat{y}, H)$, where \hat{y} is some fixed value
- In practice possible only for some simple distributions (Gaussian) and conjugate priors, still quite difficult
- Discrete distributions: sum over all values
Also possible in graphs etc. (Chapters 25, 26)
- Low-dimensional distributions can be discretized

Marginalization vs Point estimates



Laplace's approximation

- The goal is to approximate normalization constant Z of an unnormalized probability distribution, $Z = \int p(x)dx$
- Idea: Approximate the distribution by a Gaussian at the mode
- Taylor's expansion of the logarithm:

$$\ln p(x) = \ln p(x_0) - \frac{1}{2}(x - x_0)^T A(x - x_0) + \dots$$

- Needs only the posterior mode and matrix of second derivatives (Hessian matrix, $A_{ij} = -\frac{\partial^2}{\partial x_i \partial x_j} \ln p(x)|_{x=x_0}$)
- Easy to compute Z because the normalization constant of the Gaussian is known

Laplace's approximation 2/2

- Problem or opportunity:
depends on the basis, i.e., non-linear transformation changes the approximation (Exercise)
→ find a parameterization that gives approximately normal distribution
- Approximates only one mode of multimodal distributions

Occam's razor - Idea

- “Accept the simplest explanation that fits the data”
- Machine learning needs to grasp the same intuition
- Bayesian way of thinking? We could prefer simpler models by giving them larger prior
- It turns out that we do not need to make such prior assumptions. Instead, the Occam's razor is automatically achieved by Bayesian inference

Two stages of inference

- Model fitting and model comparison
- Fitting: $\text{posterior} = \frac{\text{likelihood} \times \text{prior}}{\text{evidence}} \propto \text{likelihood} \times \text{prior}$
- Comparison: $\text{posterior} \propto \text{evidence} \times \text{prior}$
- Evidence does what Occam's razor asks for

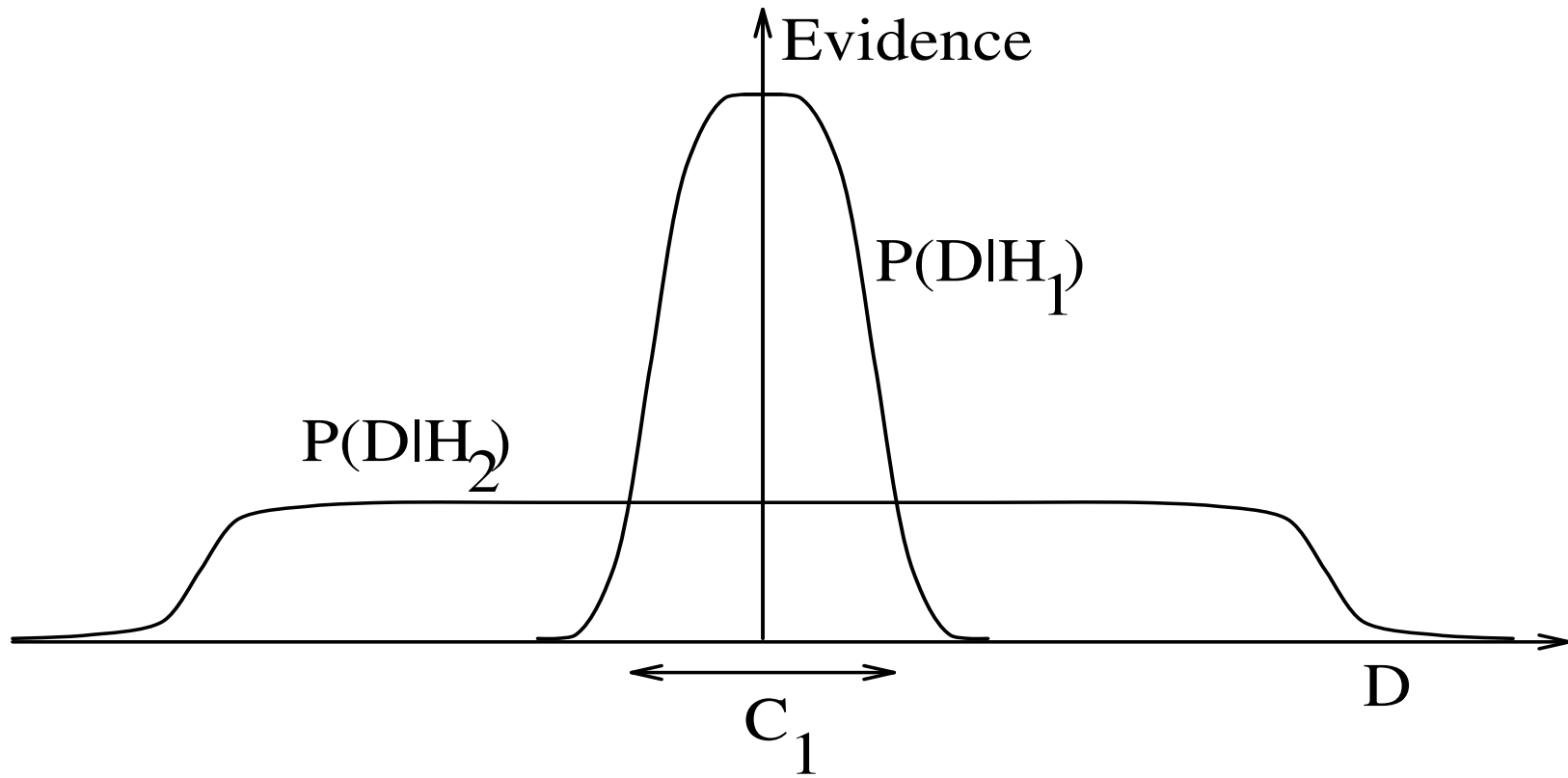
Evidence

- Posterior ratio of hypotheses

$$\frac{P(H_1|D)}{P(H_2|D)} = \frac{P(D|H_1) P(H_1)}{P(D|H_2) P(H_2)}$$

- $P(D|H) = \int P(D|w, H)P(w|H)dw$ is called the evidence of the model
- Evidence is the average probability of generating the data by randomly selecting parameter values
- Simple model: a few data sets, high evidence
- Complex model: numerous data sets, small evidence

Evidence — an illustration



What to do with evidence

- MacKay: Always average over different models, weighting each model by $P(H|D)$
- In practice we often need to select one model
- Interpreting the Bayes factor $B = \frac{P(D|H_1)}{P(D|H_2)}$:

Jeffreys (1961)		Kass, Raftery (1995)	
B	Evidence against H_2	B	Evidence against H_2
1 - 3.2	Worth mentioning	1 - 3	Worth mentioning
3.2 - 10	Substantial	3 - 20	Positive
10 - 100	Strong	20 - 150	Strong
> 100	Decisive	> 150	Very strong

Computing evidence

- Exact evidence – often impossible

$$P(D|H) = \int P(D|\mathbf{w}, H)P(\mathbf{w}|H)d\mathbf{w}$$

- Laplace's method:

$$P(D|H) \approx P(D|\mathbf{w}_{\text{MP}}, H) \times P(\mathbf{w}_{\text{MP}}|H)\sigma_{\mathbf{w}|D}$$

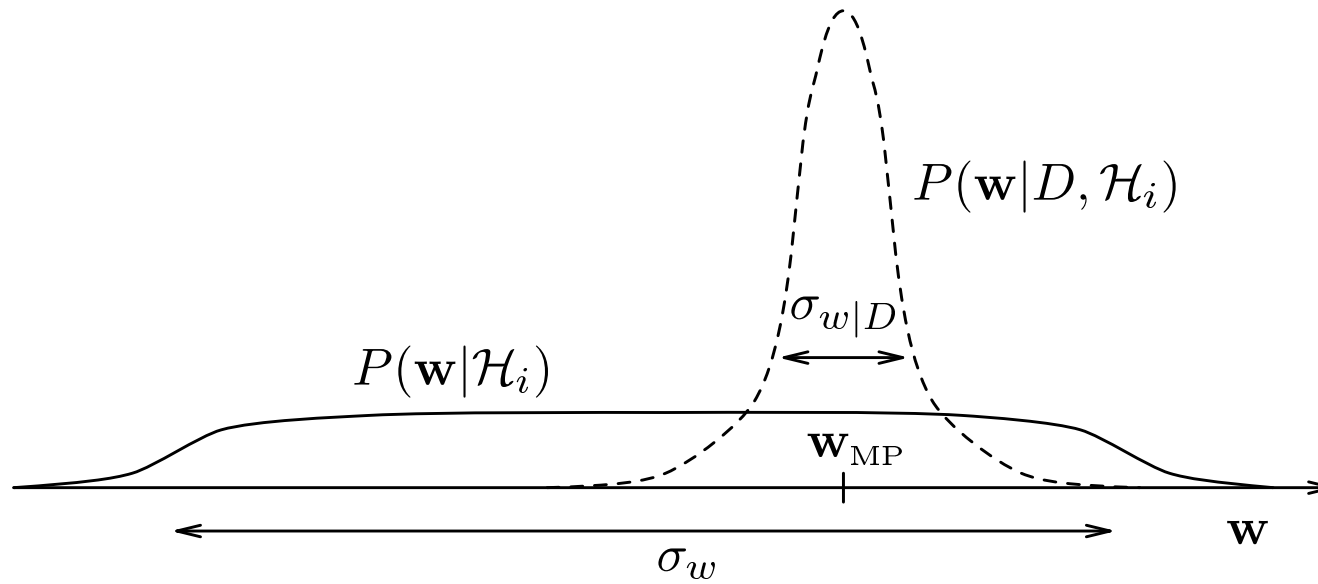
$$\text{Evidence} \approx \text{Best fit likelihood} \times \text{Occam factor}$$

- Normalization constant $\propto \sigma_{\mathbf{w}|D}$, the standard deviation of the posterior distribution
- Only MAP-estimate and error bars (Hessian) required

Occam factor

- Occam factor: $P(\mathbf{w}_{\text{MP}}|H)\sigma_{\mathbf{w}|D}$
- Interpretation: Assume flat prior, then $P(\mathbf{w}_{\text{MP}}|H) = 1/\sigma_{\mathbf{w}}$
→ Occam factor is ratio of posterior and prior widths
- The factor by which hypothesis space collapses when the data arrive
- Logarithm of the factor measures the amount of information gained about parameters when the data arrive

Occam factor — an illustration



Occam factor - Problems

- The prior has to be proper
- The factor depends on the prior
- Consider two identical models with different priors:
The one with better fitting prior has larger evidence
- Should tweaking the prior lead to higher evidence?
- Conclusion: be careful with Occam factor

Minimum description length and Occam's razor

- Instead of probabilities, consider message lengths required to communicate events without loss
- Message lengths correspond to probabilities by $L(x) = -\log_2 P(x)$
- Communicate data with two-part message: the model and the data given the model $L(D, H) = L(H) + L(D|H)$
- Sending the model means identifying what model to use and then sending the parameters of the model
- Corresponds to the Bayesian analysis:

$$L(D, H) = -\log P(H) - \log(P(D|H)\delta D) = -\log P(H|D) + \text{const}$$

Evidence and cross-validation

- Evaluating the evidence has a relation to cross-validation
- De-compose the log-evidence into

$$\log P(D|H) = \log P(x_1|H) + \log P(x_2|x_1, H) + \dots + \log P(x_n|x_1, \dots, x_{n-1}, H)$$

- Leave-one-out cross-validation measures the expectation of the last term $\log P(x_n|x_1, \dots, x_{n-1}, H)$ under data re-orderings
- Evidence, on the other hand, measures how well the whole data is predicted by the model, starting from scratch

Conclusions

- Bayesian inference consists of model fitting and comparison
- Occam's razor: prefer simpler models — automatically embodied by evidence of the model
- Computing the evidence is difficult — in practice some approximations have to be used

Exercises

- Exercise 27.1, page 342: Laplace's approximation for Poisson distribution in two bases. Compare the resulting approximations to the unnormalized posterior, and study the differences in approximation accuracy.
- Exercise 28.1, page 354: Evaluate the evidences of two competing models. For H_1 , assume uniform prior for m . Discretizing the problem is probably the easiest way of computing the evidence. Why Laplace's approximation would not be good here? How would you interpret the results?