

# HMM Adaptation for applications in Telecommunication

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## Reference:

- Hans-Günter Hirsch, **HMM Adaptation for applications in Telecommunication**, Speech Communications 34 (2001) 127-139

# Outline

- Recognition Experiments
  - Adaptation to Additive & Convolutional noise
- Application in the Telephone Network
- Conclusions



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- Introduction
- Features of the recognizer
  
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  - Estimation of Noise Spectrum
  - Estimation of Frequency Response
  - Adaptation of Cepstral Parameters
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# Introduction

- How do we have speech recognition systems in real-life situations?
- **Recognition system at a switch in a telephone network?**
- Recognizer has to cope with two main sources of noise
  - constant background noise (usually additive)
  - Channel noise (usually convolutive)
- Influence of these noise can be described as

$$Y(f) = |H(f)|^2 S(f) + N(f)$$

- where  $S(f)$  psd of clean speech,  $N(f)$ , noise spectrum,  $H(f)$ , frequency response of whole transmission system
- This paper assumes a slowly time varying channel
- **Idea:** Adapt HMM parameters with estimates of  $H(f)$  and  $N(f)$

# Features of the recognizer

- Based on representation of speech by cepstral parameters
- Feature vector has
  - 12 MEL frequency cepstral coefficients
  - 12 corresponding  $\delta$  cepstral coefficients
- Words are modeled by HMMs with the following features
  - 18 states per word
  - 4 (or 2) Gaussian Mixtures per state
  - left to right model
  - diagonal covariance matrices

# Estimation of noise spectrum

- Estimated as a weighted sum of actual and past short-term MEL spectra

$$\sqrt{\hat{N}(t_i, f)} = \alpha \sqrt{\hat{N}(t_{i-1}, f)} + (1 - \alpha) \sqrt{X(t_i, f)}$$

- $\sqrt{\hat{N}(t_i, f)}$  is the estimated magnitude noise spectrum at time  $t_i$
- Initialization, speech input is preceded only by a background noise segment
- Each sub-band update takes place as long as input spectral component  $\sqrt{X(t_i, f)}$  is below a threshold

- Exceeding the threshold, implies that there is a rise in sub-band energy, which might be due to onset of speech.
- Based on the measurement of

$$NX(f) = \sqrt{\hat{N}(t_i, f)} / \sqrt{X(t_i, f)}$$

- which is **noise-to-signal** ratio, the authors detect the presence of speech or a non-stationary segment.
- Relative NSRs, indicate if the sub-band has noise or has a speech signal. Speech flag is set if three successive frames indicate the presence of speech.

- Presence of speech triggers the HMM adaptation.

# Estimation of Frequency Response

$$|\hat{H}_{act}(f)|^2 = \frac{Y_{long}(f) - \hat{N}(f)}{\hat{S}_{long}(f)}$$

- $Y_{long}(f)$  long term spectrum assuming a constant  $H(f)$  and a constant  $N(f)$
- Long term spectra are obtained by summing up various short term spectra in the sub-bands
- Long term spectra of clean speech  $\hat{S}_{long}(f)$ , is obtained from the HMM after recognition and alignment.
- Recursively  $|\hat{H}_{act}(f)|^2$  is estimated as

$$|\hat{H}_{new}(f)|^2 = \alpha|\hat{H}_{old}(f)|^2 + (1 - \alpha)|\hat{H}_{act}(f)|^2$$

- Iterative updates results in smoothed version of frequency response
- It also compensates for the estimation errors
- Using the frequency response during the training phase, mismatches between the frequency responses of training and recognition phase can be calculated.



# Adaptation of Cepstral Parameters

- Estimates of  $N(f)$ ,  $H(f)$ , modified clean speech spectrum can be calculated.
- This modification requires transformation of the cepstral parameters back to linear spectral domain.
- All cepstral means are adapted against the various noises.
- Adapting only the cepstral parameters - **log-add** approximation
- The  $\Delta$  cepstral coefficients are adapted by

$$\Delta \hat{S}_{lg}(f) \approx \frac{S(f)}{S(f) + \hat{N}(f)} \Delta S_{lg}(f)$$

- $\Delta S_{lg}(f)$  represents the logarithmic spectral parameters when transforming back the  $\Delta$  cepstral coefficients

# Recognition Experiments

- Speaker independent recognition of digit sequences and isolated digits
- TIDIGITS data base are used for training
- Original data recorded at a high SNR
- Each digit is modeled by a single HMM consisting of a mixture of four Gaussian components per state
- Recognition is done with adding noise to the TIDIGITS and filtering them
- A Bellcore database consists of isolated digits recorded via telephone lines

# Additive Noise Adaptation

- Artificial addition of car noise to the TIDIGITS at different SNR
- Results without noise are at 30dB
- Without adaptation error rate increases, while Delta adaptation further reduces error rates
- Adaptation of Delta Coefficients and variances - worthwhile only at low SNR (**variance adaptation is an computationally expensive process**)

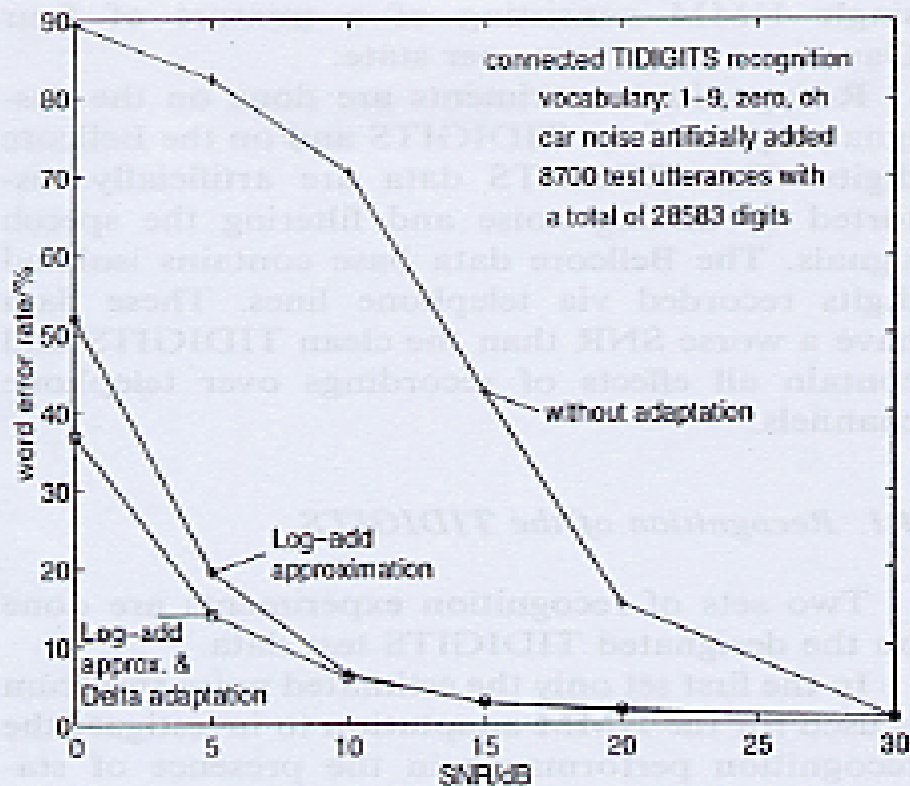


Fig. 6. Word error rates applying the Log-add approximation.

# Additive Noise Adaptation -2

- PMC (Parallel Model Combination) and Spectral Subtraction (SS)
- SS can be used as a preprocessing method that adds robustness to the recognizer
- SS alone produces significant improvement, but HMM adaptation improves the error rates further
- Leads to the hypothesis: SS might introduce certain distortions.
- **Segments with low energy and spectrally similar to noise might get attenuated which might have negative effects on the recognition process**

- Other Noise sources are helicopter noise and speech-like-noise

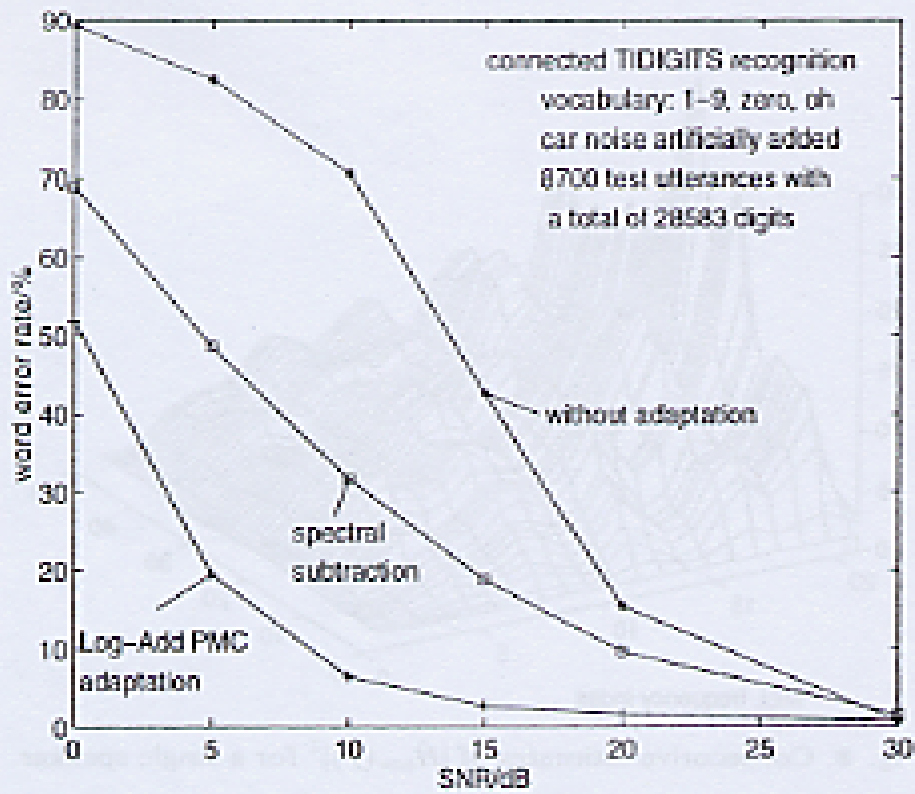


Fig. 7. Word error rates comparing the Log-add approximation against spectral subtraction.



# Additive and Convulsive Noise Adaptation

- Test data is filtered with a frequency characteristic simulating a telephone channel ( $f < 300$  Hz &  $f > 3400$  Hz attenuated by 40 dB)
- Amplification of 3dB/octave for the range 300 to 1000 Hz
- **without adaptation: 4.23 %**
- **LA with filter estimation: 0.71 %**

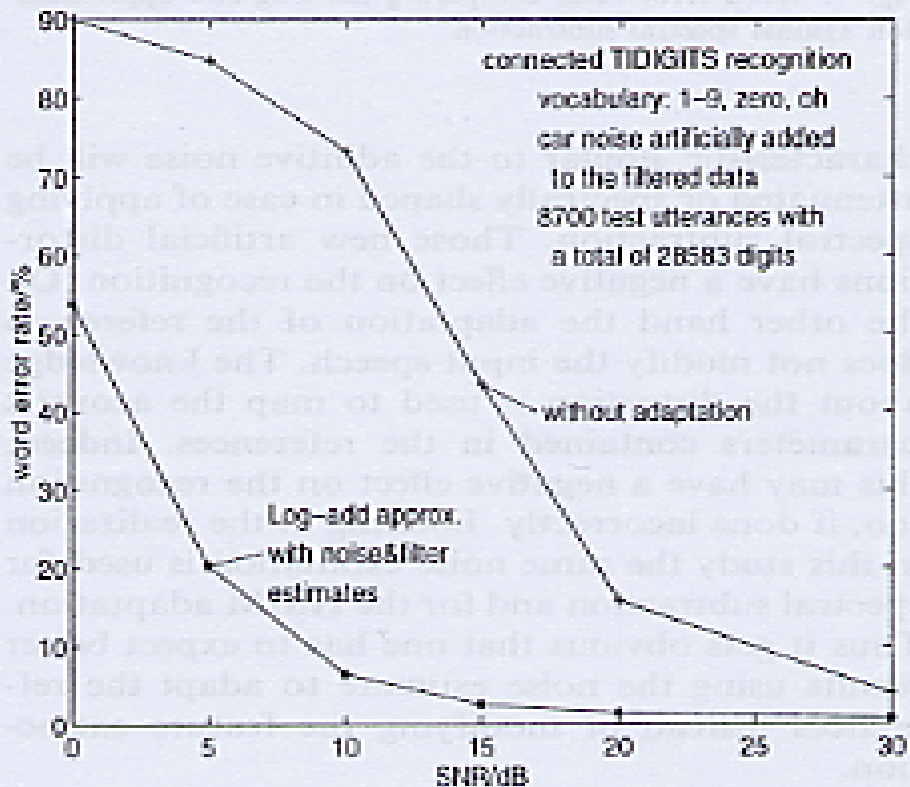


Fig. 9. Word error rates when recognizing the filtered data with car noise added.

# Telephone Network Adaptation

- Field test using a real network
- Callers utter *yes,no, results of some additions*
- PC connected to the ISDN line
- 2-gender dependent HMMs, trained from a data base of German and Swedish people speaking English
- **without adaptation: 7.98 %**
- **with adaptation: 3.47 %**

# Conclusions

- Adaptation of HMMs to
  - stationary background noise
  - Frequency mismatch between training sequences and test data
- Processing is based on PMC approaches where noise spectrum as well as frequency response are estimated
- Considerable improvements can be gained by modeling garbages (breathing before and after the speech etc)
- Results show good gains with adaptation

- Results are based on adaptation of the cepstral means, adaptation of the distributions is more complex (computationally), but should invariably lead to better results
- **Goal: integrate the recognition system to a telephone network**



