

Primal-Dual Algorithm

Sampo Syrjänen

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- ▶ general algorithm for solving LPs
- ▶ generates specialized algorithms
 - ▶ shortest paths, max flow, min-cost flow

Algorithm (preview)

procedure primal-dual

infeasible := 'no', opt := 'no'

let π be feasible in D

while infeasible = 'no' and opt = 'no' **do**

 set $J = \{j : \pi^T A_j = c_j\}$

 solve RP by the simplex algorithm

if $\xi_{opt} = 0$ **then**

 opt := 'yes'

else

if $\bar{\pi}^T A_j \leq 0$ for all $j \notin J$ **then**

 infeasible := 'yes'

else

$\pi := \pi + \theta_1 \bar{\pi}$

end if

end if

end while

Primal and Dual

$$\begin{aligned} P : \min z &= c^T x \\ Ax &= b \geq 0 \\ x &\geq 0 \end{aligned}$$

$$\begin{aligned} D : \max w &= \pi^T b \\ \pi^T A &\leq c^T \\ \pi^T &\geq 0 \end{aligned}$$

Complementary Slackness Conditions

$$\pi_i(a_i^T x - b_i) = 0 \quad \text{for all } i \quad (1)$$

$$(c_j - \pi^T A_j)x_j = 0 \quad \text{for all } j \quad (2)$$

- ▶ (1) is satisfied since P is in standard form
- ▶ what about (2) ?

Finding x

- ▶ Given feasible π
- ▶ Find x such that $x_j = 0$ whenever $c_j - \pi^T A_j > 0$
- ▶ let's consider only rows in A that satisfy $c_j - \pi^T A_j = 0$
- ▶ index set $J = \{j : c_j - \pi^T A_j = 0\}$
- ▶ x should satisfy the following

$$\sum_{j \in J} a_{ij} x_j = b_i \quad i = 1, \dots, m$$

$$x_j \geq 0 \quad j \in J$$

$$x_j = 0 \quad j \notin J$$

Restricted Primal (RP)

$$\begin{aligned} \min \xi &= \sum_{i=1}^m x_i^a \\ \sum_{j \in J} a_{ij} x_j + x_i^a &= b_i \\ x_j &\geq 0 \quad j \in J \\ x_j &= 0 \quad j \notin J \\ x_i^a &\geq 0 \end{aligned}$$

- ▶ can be solved using ordinary simplex algorithm
- ▶ optimal solution reached if $\xi_{opt} = 0$
- ▶ if $\xi_{opt} > 0$ we should look at the dual of the restricted primal (DRP)

Dual of the Restricted Primal (DRP)

$$\begin{aligned} \text{DRP : } \max w &= \pi^T b \\ \pi^T A_j &\leq 0 \quad j \in J \\ \pi_i &\leq 1 \quad i = 1, \dots, m \\ \pi_i &\geq 0 \end{aligned}$$

- ▶ let us solve this and let the optimal solution be $\bar{\pi}$
- ▶ corrected $\pi^* = \pi + \theta \bar{\pi}$
- ▶ new cost of D is $\pi^{*T} b = \pi^T b + \theta \bar{\pi}^T b$

Choosing θ

- ▶ when choosing θ
 - ▶ cost of D should increase
 - ▶ feasibility should be maintained
- ▶ the optimal costs of RP and DRP are equal at mutual optimality since they are a primal-dual pair
 $\bar{\pi}^T b = \xi_{opt} > 0$
- ▶ cost of D was $\pi^{*T} b = \pi^T + \theta \bar{\pi}^T b$
- ▶ $\theta > 0$ to increase the cost of D

- ▶ feasibility must be maintained
- ▶ in D we have $\pi^{*T} A_j = \pi^T A_j + \theta \bar{\pi}^T A_j \leq c_j$
- ▶ if $\bar{\pi}^T A_j \leq 0$ for every j
 - $\Rightarrow \theta$ can be chosen arbitrarily large
 - $\Rightarrow D$ is unbounded
 - $\Rightarrow P$ is infeasible
- ▶ For all $j \in J$, $\bar{\pi}^T A_j \leq 0$ since $\bar{\pi}$ is optimal
- ▶ feasibility is maintained when $\bar{\pi}^T A_j > 0$ for some $j \notin J$
- ▶ $\theta_1 = \min_{\{j \notin J | \bar{\pi}^T A_j > 0\}} \left[\frac{c_j - \pi^T A_j}{\bar{\pi}^T A_j} \right]$

Algorithm

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Demonstration, Shortest Path Problem

$$\begin{aligned} \min c^T f \\ Af = \begin{bmatrix} +1 \\ 0 \\ \cdot \\ \cdot \\ \cdot \\ 0 \end{bmatrix} & \leftarrow \text{Row } s \\ f \geq 0 \end{aligned}$$

$$\begin{aligned} & \max \pi_s \\ & \pi_i - \pi_j \leq c_{ij} \quad \text{for all arcs } (i,j) \in E \\ & \pi_i \geq 0 \quad \text{for all } i \\ & \pi_t = 0 \end{aligned}$$

$$\min \xi = \sum_{i=1}^{m-1} x_i^a$$

$$Af + x^a = \begin{bmatrix} +1 \\ 0 \\ \cdot \\ \cdot \\ \cdot \\ 0 \end{bmatrix} \quad \leftarrow \text{Row } s$$

$$f_j \geq 0 \quad \text{for all } j$$

$$f_j = 0 \quad j \in J$$

$$x_i^a \geq 0$$

$$\begin{aligned} & \max \pi_s \\ & \pi_i - \pi_j \leq 0 \quad \text{for all arcs } (i, j) \in J \\ & \pi_i \leq 1 \quad \text{for all } i \\ & \pi_i \geq 0 \end{aligned}$$