T-122.102 Special Course in Information Science VI:
Co-occurence methods in analysis of discrete data
Kernels for Structured Data

Based on article: A Survey of Kernels for Structured Data by Thomas Gärtner

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## Outline

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## Introduction

- Kernel methods have become popular in supervised learning (classification, regression), but also in unsupervised learning (clustering, PCA).
- For example, a nonlinear classifier is obtained by mapping the data from input space into a feature space via nonlinear mapping, and solving the classification problem in the feature space.
- The data is mapped into feature space, and a simple classifier or function is fitted to the data
- A global solution for the optimization problem is obtained
- The parameter optimization is performed with traditional nonlinear programming methods.


## The kernel trick

- Let's select a mapping $\Phi$ from (continuous!) input space to feature space as:

$$
\Phi:\left(x_{1}, x_{2}\right) \rightarrow\left(x_{1}^{2}, \sqrt{2} x_{1} x_{2}, x_{2}^{2}\right)
$$

- To see that this corresponds to kernel $K\left(x, x^{\prime}\right)=\left\langle x, x^{\prime}\right\rangle^{2}$ :

$$
\begin{aligned}
K\left(x, x^{\prime}\right) & =\left\langle x, x^{\prime}\right\rangle^{2}=\left(x_{1} x_{1}^{\prime}+x_{2} x_{2}^{\prime}\right)^{2} \\
& =\left(x_{1} x_{1}^{\prime}\right)^{2}+2 x_{1} x_{2} x_{1}^{\prime} x_{2}^{\prime}+\left(x_{2} x_{2}^{\prime}\right)^{2} \\
& =\left\langle\left(x_{1}^{2}, \sqrt{2} x_{1} x_{2}, x_{2}^{2}\right),\left(x_{1}^{\prime 2}, \sqrt{2} x_{1}^{\prime} x_{2}^{\prime}, x_{2}^{\prime 2}\right)\right\rangle \\
& =\left\langle\Phi(x), \Phi\left(x^{\prime}\right)\right\rangle .
\end{aligned}
$$

- The mapping $\Phi$ is not explicitly needed. Instead, one can evaluate the value of the kernel function $K\left(x, x^{\prime}\right)$.


## Example: Nonlinear regression with SVM

- In support vector regression, the optimization problem is:

$$
\begin{array}{ll}
\text { maximize } & -\frac{1}{2} \sum_{i, j=1}^{m}\left(\alpha_{i}-\alpha_{i}^{*}\right)\left(\alpha_{i}-\alpha_{i}^{*}\right) K\left(x_{i}, x_{j}\right) \\
& -\varepsilon \sum_{i=1}^{m}\left(\alpha_{i}+\alpha_{i}^{*}\right)+\sum_{i=1}^{m} y_{i}\left(\alpha_{i}-\alpha_{i}^{*}\right) \\
\text { subject to } & \sum_{i=1}^{m}\left(\alpha_{i}-\alpha_{i}^{*}\right)=0, \alpha_{i}, \alpha_{i}^{*} \in[0, C / m],
\end{array}
$$

- Once the free parameters of the objective function $\left(\alpha_{i}, \alpha_{i} *\right)$ are obtained, the estimated nonlinear function becomes

$$
f(x)=\sum_{i=1}^{m}\left(\alpha_{i}-\alpha_{i}^{*}\right) K\left(x_{i}, x\right)+b
$$

## Valid and good kernels

- Kernel $K\left(x, x^{\prime}\right)$ measures the similarity of $x$ and $x^{\prime}$.
- Valid kernel: the kernel function $K\left(x, x^{\prime}\right)$ is positive definite.
- Goodness of a kernel: completeness, correctness, appropriateness
- Completeness refers to the extent to which the knowledge incorporated to the kernel is sufficient for solving the problem at hand.
- Correctness refers to the extent to which the underlying semantics of the problem are obeyed in the kernel.
- Appropriateness refers to the extent to which the examples that are close to each other in the class membership are also close to each other in the feature space.


## Kernels from generative models

- Let us assume that we have a set of possible states $s_{i}, i=1, \ldots, N$, and a state transition matrix $A$ of size $N \times N$, where $A_{i j}$ captures the probability of the system to switch from state $s_{i}$ to $s_{j}$.
- A generative model for the system is of the form $P(s \mid \theta)$, where $\theta$ consists of the probabilities in the matrix $A$.
- Let $U_{x}$ be the gradient of the log-likelihood w.r.t the parameters of the generative model $P(x \mid \theta)$ at $x$ :

$$
U_{x}=\nabla_{\theta} \log P(x \mid \theta)
$$

- $U_{x}$ captures the rate of change of the parameters at given observation $x$. Posterior distribution $P(\theta \mid x)$ would only provide the most likely parameters responsible for generating the observations.
- A kernel that can be used to process sequences that are produced by a generative model $P(x \mid \theta)$ is

$$
K\left(x, x^{\prime}\right)=U_{x}^{T} U_{x}
$$

- Often, the kernel is equipped with the Fisher information matrix I over the distribution $P(x \mid \theta)$ :

$$
I=E\left\{U_{x} U_{x}^{T}\right\}
$$

yielding into so-called Fisher kernel:

$$
K\left(x, x^{\prime}\right)=U_{x}^{T} I^{-1} U_{x}
$$

## Diffusion kernel

- The diffusion kernels are of the form

$$
K=e^{\beta H}=\lim _{n \rightarrow \infty}\left(1+\frac{\beta H}{n}\right)^{n},
$$

where $\beta$ is so-called bandwidth parameter and $H$ is a generator.

- Differentiating with respect to $\beta$ leads into differential equation

$$
\frac{d}{d \beta} K(\beta)=H K(\beta) .
$$

- Selecting initial conditions $K(0)=I$ leads into interpretation that $K(\beta)$ is the product of continuous process, expressed by $H$, gradually transforming it from identity matrix $K(0)$ to a kernel with stronger and stronger off-diagonal effects as $\beta$ increases.
- Choosing $H$ to express the local structure of input data will result in the global structure of the input data naturally emerging in $K$.
- Example: an undirected graph $G$ is defined by a vertex set $V$ and an edge set E , where $\left\{v_{i}, v_{j}\right\} \in E$ if there is an edge between vertices $v_{i}$ and $v_{j}$.
- A suitable generator is

$$
H_{i j}= \begin{cases}1 & ,\left\{v_{i}, v_{j}\right\} \in E \\ -d_{i} & , i=j \\ 0 & , \text { otherwise }\end{cases}
$$

where $d_{i}$ is the number of edges originating from vertex $v_{i}$.

## Convolution kernels

- The semantics of the composite objects can often be captured by a relation $R$ between the object and its parts.
- Let $\vec{x}=x_{1}, x_{2}, \ldots, x_{d}$ denote the parts of object $x$, and $R$ be a relation on the set $X_{1} \times X_{2} \times \ldots \times X_{d} \times X$.
- $R(\vec{x}, x)$ is true iff $x_{1}, x_{2}, \ldots, x_{d}$ are the parts of $x$.
- Let $R^{-1}(x)=\{\vec{x}: R(\vec{x}, x)\}$ be the set of parts of $x$.
- Let us assume, that kernel $K_{d}\left(x_{d}, x_{d}^{\prime}\right)$ measures the similarity of part $d$ of the objects $x$ and $x^{\prime}$.
- Then, a convolution kernel suitable for measuring the similarity of composite objects $x$ and $x^{\prime}$ is:

$$
K\left(x, x^{\prime}\right)=\sum_{\vec{x} \in R^{-1}(x), \vec{x}^{\prime} \in R^{-1}\left(x^{\prime}\right)} \prod_{d=1}^{D} K_{d}\left(x_{d}, x_{d}^{\prime}\right)
$$

## String kernels

- The similarity of two strings $s_{1}$ and $s_{2}$ (and thus, the value of the kernel function $\left.K\left(s_{1}, s_{2}\right)\right)$ depends on the number of common subsequences.
- Gaps within the subsequences are penalized.
- Consider two strings $s_{1}=$ "cat" and $s_{2}=$ "cart".
- Common subsequences are "c", "a", "t", "ca", "at", "ct", "cat".
- Now, the total length of occurences of these subsequences in $s_{1}$ and $s_{2}$ are (w.r.t $s_{1}$, w.r.t $s_{2}$ ): "c" $(1,1)$, "a" $(1,1)$, "t" $(1,1)$, "ca" (2,2), "at" (2,3), "ct" (3,4), "cat" (3,4).
- Now, using a decay factor $\lambda$, penalties corresponding to the subsequences become "c": $\lambda^{1} \lambda^{1}$, "a": $\lambda^{1} \lambda^{1}$, "t": $\lambda^{1} \lambda^{1}$, "ca": $\lambda^{2} \lambda^{2}$, "at": $\lambda^{2} \lambda^{3}$, "ct": $\lambda^{3} \lambda^{4}$, "cat": $\lambda^{3} \lambda^{4}$.
- Now, the value of the kernel function between two strings $s_{1}$ and $s_{2}$ is the sum of the penalties:

$$
K\left(\text { "cat","cart") }=2 \lambda^{7}+\lambda^{5}+\lambda^{4}+3 \lambda^{2}\right.
$$

- Computation of the value of this kind of kernels may be very expensive.


## Tree kernels

- The instances considered in the learning task are labeled, ordered directed subtrees.
- Consider some enumeration of all possible subtrees and let $h_{i}(T)$ be the number of occurences of $i$ th subtree in tree $T$.
- In order to measure the similarity of two trees $T_{1}$ and $T_{2}$, the value of the kernel

$$
K\left(T_{1}, T_{2}\right)=\sum_{i} h_{i}\left(T_{1}\right) h_{i}\left(T_{2}\right)
$$

can be computed.

## Basic term kernels

- Key idea: fixed type structures.
- Three kind of types: function types, product types and constructor types.
- function types for sets and multisets
- product types for tuples
- constructors for arbitrary size structural objects (lists, trees, etc.)
- Each type defines basic terms representing the instances of the types.
- Abstraction is used to build instances of function type, tupling is used to create instances of product type and application corresponds to building objects of a type constructor.
- Examples: basic term $s$ represents the set $\{1,2\}$ and basic term $t$ represents the multiset with 42 occurences of $A$ and 21 occurences of $B$ :

$$
\begin{aligned}
s & =\lambda x . \text { if } x=1 \text { then } \top \text { else if } x=2 \text { then } \top \text { else } \perp \\
t & =\lambda x . \text { if } x=A \text { then } 42 \text { else if } x=B \text { then } 21 \text { else } 0
\end{aligned}
$$

- For basic abstraction $r, V(r u)$ denotes the value of $r$ when applied to $u$. For example, $V(s 2)=\top$ and $V(t C)=0$.
- Support of an abstraction is the set of terms $u$ for which $V(r u)$ differs from default value. For example, $\operatorname{supp}(s)=\{1,2\}$.
- Now, if $s$ and $t$ are basic terms formed by abstraction, then a suitable kernel to measure their similarity is:

$$
K(s, t)=\sum_{u \in \operatorname{supp}(s), v \in \operatorname{supp}(t)} K(V(s u), V(t v)) \cdot K(u, v)
$$

## Graph kernels

- A graph consist of a set of vertices, a set of edges between the vertices, a set of labels for the vertices and a set of labels for the edges.
- Two graphs generating a product graph are called factor graphs.
- The vertex set of the product graph is Cartesian product of the vertex sets of the factor graphs.
- The product graph has a vertex iff the labels of the corresponding vertices in the factor graphs are the same.
- There is an edge between two vertices in the product graph if there is an edge between the corresponding vertices in both factor graphs and both edges have the same label.
- Let's denote the edge set of the product graph by $\mathcal{E}_{\times}$.
- Let's denote an enumeration of vertex set by $\mathcal{V}=\left\{v_{i}\right\}$, $i=1, \ldots, N$.
- The elemenents of the so-called adjacency matrix $E_{\times}$are defined by $\left[E_{\times}\right]_{i j}=1 \Longleftrightarrow\left(v_{i}, v_{j}\right) \in \mathcal{E}_{\times}$, and $\left[E_{\times}\right]_{i j}=0 \Longleftrightarrow$ $\left(v_{i}, v_{j}\right) \notin \mathcal{E}_{\times}$.
- With a sequence of weights $\lambda_{0}, \lambda_{1}, \ldots,\left(\lambda_{i} \geq 0, \forall i\right)$, the value of the product kernel between two graphs $G_{1}$ and $G_{2}$ is:

$$
K_{\times}\left(G_{1}, G_{2}\right)=\sum_{i, j=1}^{\left|\mathcal{V}_{\times}\right|}\left[\sum_{n=0}^{\infty} \lambda_{n} E_{\times}^{n}\right]_{i j}
$$

where $\left[E_{\times}^{n}\right]_{i j}$ is the number of walks of length $n$ from $v_{i}$ to $v_{j}$.

## Conclusions

- Kernel methods, especially for structured data is a promising research area.
- For discrete data, the problem reduces in selecting a suitable kernel. In the literature, a lot of kernels have been proposed.
- The selection of a suitable kernel for the problem at hand is not a trivial task.
- A lot of applications for processing sequences describing DNA, protein, gene, speech, text, molecule, etc. are presented.

